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MODIFICATION OF AXIAL COMPRESSOR
STREAMLINE PROGRAM FOR ANALYSIS
OF ENGINE TEST DATA

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MODIFICATION OF AXIAL COMPRESSOR STREAMLINE PROGRAM
FOR ANALYSIS OF ENGINE TEST DATA

by Jeffrey G. Williams

SUMMARY

This report describes modifications of an existing axial compressor streamline analysis computer program to allow input of measured radial pressure and temperature profiles obtained from engine or cascade data. The proposed modifications increases the input flexibility and are accomplished without changing the computer program's input format. The computer program was written by Richard M. Hearsey under a grant from the Aerospace Research Laboratory at Wright-Patterson Air Force Base. Since this report is intended to supplement the above computer program, the reader is referred to Hearsey's reports for theory, complete program listings, and detailed user's instructions.

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INTRODUCTION

Detailed flow field information is important in both axial compressor analysis and design. In fan and compressor designs, this information permits evaluation of proposed improvements through efficiency calculations. In flutter research, accurate flow information gives blade incidence or angle of attack which specifies the steady state pressure distribution and hence internal blade stresses. Likewise, in stall investigations, accurate blade incidence is of primary concern.

The precision required determines which two or three-dimensional axisymmetric analysis to use. Two dimensional programs (radial velocities equal to zero) can be reasonably accurate for hub-to-tip radius ratios less than 0.8. However three-dimensional analyses must be utilized whenever radial velocities become significant. There are several such analyses that are worthy of consideration. Radial equilibrium is quite popular but requires different equations for axial stations located interior and exterior to blade rows (ref. 1). Actuator Disk Theory, on the other hand, is rather difficult to use in practice because of the closeness of 'disks' in an axial compressor (ref. 2). The Streamline Curvature technique is extremely powerful but requires at least medium computer capability (ref. 3).

Of the several streamline curvature analyses in existence, Richard Hearsey's analysis and computer pro-

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gram (refs. 4 & 5) can satisfy a variety of user requirements. A partial listing of these program possibilities can be found in Appendix B. The computer program is written in three sections which include the aerodynamic streamline analysis section and two blade design sections. All parts of the program are well documented and written in standard FORTRAN IV. Reference 4 presents the theory and detailed user's instructions while reference 5 gives program listing and two examples.

Despite the versatility of Hearsey's program, the aerodynamic section of the program does not accept direct input of engine or cascade test data. This report is intended to supplement reference 4 and describes modifications to several of the aerodynamic section subroutines to allow direct input of radial pressure and temperature profiles. In addition, modifications to the CALCOMP subroutine are proposed to provide compatibility with an earlier version of the plotting package. Finally, an example is prepared and run to show that the modifications are acceptable.

DISCUSSION

Streamline Computational Technique

Streamline curvature analysis is a means to solve for the velocity triangles in an axial compressor. The typical two-dimensional velocity triangles for rotors and stators (fig. 1) are extended to the radial direction to account for radial velocities which can be significant. Symmetry is assumed in the circumferential direction to simplify the analysis.

The flow field grid is established by the intersection of streamlines with specified axial stations. These axial stations may be inserted at strategic locations in the flow field such as leading and trailing blade edges or instrumentation sites. Generally, however, several stations must be specified upstream and downstream of the region of interest to define inlet and outlet conditions. The program will produce output for all defined axial stations.

The compressible flow equations are restructured and written in terms of radial, circumferential and meridional components (ref. 4). The meridional direction, shown in figure 2, lies in the radial-axial plane. These flow equations, which contain streamline curvature and slope terms, are solved given an initial guess for the streamline pattern. The program iterates, each time improving the streamline pattern until the specified tolerance is achieved. Program output consists of velocity triangle components, flow angle, streamline curvature, and thermodynamic information as a function of radius.

Aerodynamic Subroutine Modification

The aerodynamic section of Richard Hearsey's computer program (ref. 4) allows a variety of input data combinations for the rotor and stator axial stations.* 'W rk' input (DATA1) can be expressed as: Total pressure, total enthalpy, absolute angular momentum, absolute whirl velocity or relative flow angle. 'Loss' input (DATA2) can be of the form: Relative total pressure loss coefficient, isentropic efficiency, or

*The author assumes that the reader has an understanding of the aerodynamic (or streamline) section of the reference 4 computer program and is familiar with the terminology and organization of the input deck.

entropy rise. The appropriate values of DATA1 and DATA2 are input at each axial location as a function of radius or passage height.

Typically, a researcher has correlated engine or cascade data in terms of radial pressure and temperature profiles behind rotors and pressures and flow angles (blade metal angle plus deviation angle) behind stators. Figure 3 shows the typical instrumentation of a compressor cascade. To use Hearsey's program in its present form the most favorable input combination would then be: Total pressure (DATA1, NWORK = 1) and isentropic efficiency (DATA2, NLOSS = 2) as input behind rotors and flow angle (DATA1, NWORK = 5, 6, or 7) and relative total pressure loss coefficient (DATA2, NLOSS = 1) as input behind stators.* This input selection minimizes the conversion from 'raw' data to program compatible data.

Modifications can be made to the computer program to allow direct input of station radial pressures and temperatures obtained from the cascade instrumentation. This will permit: Total pressure (DATA1) and total temperature (DATA2) as input behind rotors and flow angle (DATA1) and total pressure (DATA2) as input behind stators. Clearly these are the most advantageous input combinations when raw cascade data is available. The program modifications should be such that the original input combinations remain available to those researchers who might wish to use them. The modification scheme detailed below allows for this input flexibility.

Aerodynamic section subroutines UD0302 and UD0307 must be modified to allow total temperature input (DATA2) behind rotors and total pressure input (DATA2) behind stators. Subroutine UD0302 reads the input combinations at each station and does appropriate units conversions. Subroutine UD0307 converts the station data into streamline entropy and enthalpy to be used by the main driving program, UD03AR.

The modification concept involves sensing the magnitude of the input data and directing subroutine UD0307 to the correct computation of entropy and enthalpy utilizing the available thermodynamic subrou-

*The term 'relative' is misleading here but is used extensively throughout the reference 4 program instructions. Appendix C shows that the relative loss coefficient reduces to the absolute total pressure loss coefficient in stator passages.

tines, UDG1 through UDG9. For example, for stations behind rotors, total pressure (DATA1, NWORK = 1) is an acceptable input. Also, the magnitude of the isentropic efficiency (DATA2, NLOSS = 2) should never exceed 1.0. The modified program checks the magnitude of this 'loss' and if greater than 1.0, assumes the input is absolute total temperature. Subroutine UD0307 can then compute enthalpy and entropy for these stations using thermodynamic routines UDG2 and UDG3 respectively. Hence, pressure and temperature data become a suitable input combination behind rotors. A listing of the modified subroutine, UD0307, which contains this limit checking sequence appears in Appendix D. Lines 61 - 65 and 69 - 72 contain the specific changes for rotor stations.

Similar modifications are incorporated in subroutine UD0307 to handle stations behind stators. At these locations, flow angle (DATA1, NWORK = 5, 6, or 7) is an acceptable input. The relative total pressure loss coefficient (DATA2, NLOSS = 1) should be a small positive number. In fact, for efficient compressor blading, the relative total pressure loss coefficient should be less than 0.3. In this instance, however the magnitude of the loss coefficient does not have an upper limit as did the isentropic efficiency. An arbitrary limit value of 2.0 was chosen assuming the magnitude of the total pressure (in any chosen set of program acceptable units) should never be smaller than this value. Again the magnitude checking procedure is called upon to scan for input data greater than the limit value of 2.0. If this condition is satisfied for all of the station input data, the program assumes total pressure as input instead of loss coefficients. The modified UD0307 subroutine can then calculate entropy from the total pressure input and the enthalpy of the previous station using subroutine UDG3 (i.e. enthalpy is assumed constant across stator passages). Subroutine UD0302, the input routine, also needs the limit checking sequence because a units conversion may be required depending on the value of the scaling factor, SCLFAC. Subroutine UD0307, lines 142 - 146 and 158 - 160, and subroutine UD0302, lines 190 - 198 contain the specific modifications to allow the input combination of flow angle and total pressure behind stationary blades. A source listing of UD0302 may be found in Appendix E.

CALCOMP Subroutine Modification

Several different versions of the well-known CALCOMP plotting package exist. The main difference in the versions is the number of arguments in the subroutine calls to the individual CALCOMP routines. Hearsey's program was written utilizing the 1970 version of the plotting package (ref. 6).

The 1964-65 Version 5 CALCOMP package requires additional arguments in the 'CALL' statements to routines AXIS and LINE. The AXIS routine needs one additional argument, DV, which indicates the number of divisions per ten inches of paper to be drawn on the axis. The LINE routine requires four additional arguments - XMIN, DX, YMIN, and DY. XMIN and YMIN are minimum coordinate values on the graph. DX and DY represent the division mark incremental value for the respective axis.

Subroutine UD0312, the plotting routine in the aerodynamic or streamline section of Hearsey's program, has several CALCOMP calls to routines AXIS and LINE. This subroutine is responsible for plotting static pressure distributions (NPLOT = 1) and final streamline mesh (NPLOT = 2). A 1964-65 Version 5 compatible listing of subroutine UD0312 may be found in Appendix F.

Example

Steady state data from a NASA-Lewis full scale engine test is used as input to the modified version of Richard Hearsey's aerodynamic program (ref. 4) detailed in this report and an industry developed streamline program. The industry program makes for a good comparison because it was developed for analysis of engine test data and hence accepts radial pressure and temperature distributions directly. This industry program, however, is not as flexible as the reference 4 program nor is it available to the general public.

The analysis concentrates on the three stage fan module at the inlet of a typical modern turbofan engine. The axial stations for computer output are defined and numbered in Figure 4. Stations at leading and trailing edges of blades follow the blade lean in the axial direction. Radial total pressure and temperature profiles were available behind the first two rotors and behind the flow straightener (F.S.). Flow angle was measured at only one axial location - behind the inlet guide vane (IGV). The deviation angles behind the remaining stationary blades are assumed to be zero; that is, the flow angle equals the trailing edge

blade metal angle at these locations. From calibration plots for the flow angle probe and individual probe measurements, total pressure can be obtained thus allowing pressure loss input for the IGV (ref. 7).

Figure 5 shows the non-dimensional pressure profile behind the IGV. Because of flow angle probe structural limitations data was only obtained in the upper 40 percent of the annulus. The remainder of the curve represents an approximate profile. Total pressure profiles at other locations are shown in Figures 6, 7, and 8; total temperature profiles are shown in Figure 9. In all figures zero percent span corresponds to the fan hub. Approximate stator losses for stator 1, stator 2, and the flow straightener were computed from blade geometry and NACA tables (ref. 8).

Station input data is entered into the aerodynamic section of the reference 4 computer program in the following manner:

Station 1:

Constant pressure,
 $P_1 = 136.907 \text{ kPa}$
(19.856 psia), and
temperature, $T_1 =$
442.82K (797.08R),
exist across engine
inlet annulus. Whirl
angle is assumed to be
zero.

Stations 2-4

No data is input
(NDATA = 0). These
stations are used to
establish the flow
field at the inlet.

Station 5, IGV inlet:

Constant entropy
(NWORK = 0) from
previous station (NLL
= -1) assumed for five
radial points (NDATA =
5).

Station 6, IGV
outlet:

Twenty-one data points
(NDATA = 21) specify
flow angle (NWORK = 6)
and total pressure
(NLOSS= 1) as a func-
tion of radius.
 $136.392 < P < 136.795$
kPa.

Station 7, first
rotor inlet: No data is input.

Station 8, first
rotor outlet: Twenty-one data points specify total pressure (NWORK = 1) and total temperature (NLOSS = 2) as a function of radius. $473.82 < T < 495.96$ K.

Notice that the modified reference 4 program is called upon to accept total pressure input for a stator station (station 6) and total temperature input for a rotor station (station 8). At station 6, the magnitude of all DATA2 (NLOSS = 1) input is greater than the arbitrary limit value of 2.0, hence total pressure input is assumed. At station 8, the magnitude of all DATA2 (NLOSS = 2) input is greater than the limit value of 1., hence total temperature input is assumed. The next nine stations (9 - 17) follow the pattern established by stations 5 - 8 above. The last three stations, 19 - 21, set the outlet conditions. Input data at all points is interpreted by a spline fit (NTERP = 0) and read in as a function of percent radial span (NDIMEN = 3). A constant annulus wall boundary layer thickness is assumed for all axial stations.

The subsonic solution (NMACH = 0) to the flow field was obtained at all specified axial stations. The modified reference 4 computer program converged to within a tolerance of 0.3 percent (TOLNCE = 0.003) after 53 iterations. Output for all twenty-one streamlines at each station consist of velocity components, radius of curvature, pressures, temperatures, and flow angles. The industry program was prepared and run with the same input information. The result was convergence to within tolerance of 0.25 percent after 38 iterations.

Computer output for stations 7 and 8 for the modified reference 4 program and the industry program is compared in figures 10 through 15. Figures 10, 11, and 12 compare total pressure, total temperature, and flow angle, respectively. Figures 13, 14, and 15 compare the velocity triangle components: Meridional, radial, and relative velocity. In these figures, the modified reference 4 program output is symbolized with triangles while the industry program output appears as circles. All data is expressed as normalized ratios with the normalization constant as indicated on each graph.

Relatively good agreement is obtained between the modified reference 4 computer program and the industry program. The greatest variations in the output of the two streamline analyses appears at the annulus boundaries. This is probably due to different methods of handling the boundary information or differences in the internal program interpolation (spline fitting) routines. This is best evidenced in Figures 10(b) and 11(b). In both figures the industry program output deviates from both the reference 4 program output and the specified pressure and temperature input profiles at the fan hub (zero percent span). This discrepancy leads to differences in velocity and flow angle which can be seen in the remaining figures.

The significance of this output discrepancy depends on the initial purpose of the analysis. As an example, the maximum difference in station 7 blade hub inlet flow angle, from Figure 12(a), is approximately 3.39° ($-3.08^\circ < \alpha < 0.31^\circ$). This change in inlet flow angle at the hub will not greatly affect the overall blade pressure distribution because of the good agreement in flow angle output at spans greater than 10 percent. However, since the onset of stall flutter is sensitive to steady state blade incidence (ref. 9), this flow angle difference at the hub could be a concern.* Since the pressure and temperature output of the modified reference 4 computer program matches the pressure and temperature input profiles at stations 7 and 8, velocity components, flow angles, and remaining thermodynamic output is more credible than the industry program output.

Despite the differences in output from the two computer programs, a three dimensional analysis is much more accurate than a two-dimensional (radial velocity equal to zero) analysis. A two-dimensional program run by the author gave a station 7 flow angle of 14.15° . The modified reference 4 program shows that the true station 7 flow angle ranges from -3.08° at the hub to 14.56° near 75 percent span. The relative magnitudes of the velocity components, shown in Figures 13, 14, and 15 also indicate the significance of the radial velocity for this example.

*If this difference in blade inlet flow angle had occurred at the blade tip, a more serious situation would result because the blade is more critically loaded in this area.

Figures 16 and 17 demonstrate the modified CALCOMP plotting routine, UD0312, in the aerodynamic section of the modified reference 4 program. Figure 16 is a streamline plot which shows the streamline contraction through the fan module. The static pressure distribution for the hub, mid, and tip streamlines for the fan is shown in Figure 17.

SUMMARY OF RESULTS

The aerodynamic section of Richard Hearsey's axial compressor streamline computer program was successfully modified to allow direct input of measured radial pressure and temperature profiles obtained from engine or cascade data. Subroutines UD0302 and UD0307 contain the specific modifications to permit the input combination of flow angle and total pressure for stators and the input combination of total pressure and total temperature for rotors. All modifications were accomplished without changing the computer program's original input format.

The internal CALCOMP subroutine, UD0312, which plots streamline mesh and static pressure distributions, was modified to be compatible with an old version (1964-65, Version 5) of the plotting package. The user must decide which version of UD0312 satisfies his computer facility requirements.

The included example demonstrated how to construct the input deck for the aerodynamic section of the modified Hearsey program. The modified program was run and the results were compared with an industry program which accepted radial pressure and temperature profiles directly. Good agreement was obtained from the two analyses which indicates that the modifications to Hearsey's program were acceptable.

APPENDIX A

Symbols:

P total pressure, Pa
Pr relative total pressure, Pa
p static pressure, Pa
T total temperature, R
 ρ static density, Kg/m³
 $\bar{\omega}$ relative total pressure loss coefficient
 α absolute flow angle, deg
 β relative flow angle, deg
C absolute velocity, m/sec
W relative velocity, m/sec
U 'bucket' or rotor velocity, m/sec

Subscripts:

x axial direction
y tangential direction
r radial direction
m meridional direction
A rotor inlet
B rotor outlet
1-21 axial station identifier

APPENDIX B

The following list highlights the flexibility built into Richard Hearsey's Axial Compressor Program, references 4 and 5. Some of the specific program capabilities are:

1. Versatility to use program for design, off-design, and analysis computations.
2. Allow intrablade station locations.
3. Two forms of momentum equation to calculate subsonic and supersonic solutions of the flow field.
4. Allow input in any set of consistent units.
5. Ability to specify inlet flow distributions.
6. Ability to run program without specifying some nonzero loss criterion.
7. Multiple speed runs without inputting entire deck (just specify percent 'design' speed).
8. Plots of midstreamline position showing convergence or divergence of analysis versus iteration at each station location.
9. CALCOMP plots of final streamline mesh and static pressure distribution.
10. NASTRAN compatible output (pressure difference for calculation of blade stresses).
11. Code does blade design as well as aerodynamic streamline calculation.
12. Arbitrary blade shapes can be designed.

APPENDIX C

In stator passages, the relative total pressure loss coefficient reduces to the absolute total pressure loss coefficient as follows:

A subscript implies stator inlet.
 B subscript implies stator outlet.

Symbol definitions from Hearsey's program instructions, reference 4 and figure 1:

\Pr' - Isentropic relative total pressure
 \Pr - Relative total pressure
 P - Total pressure
 p - Static pressure
 ρ - Density

$$\bar{\omega} = \frac{\Pr' - \Pr}{\Pr_A - p_A}$$

For incompressible flow:

$$\Pr' = \Pr_A = p_A + 1/2 \rho w_A^2$$

$$\Pr = \Pr_B = p_B + 1/2 \rho w_B^2$$

$$\bar{\omega} = \frac{\Pr_A - \Pr_B}{1/2 \rho w_A^2}$$

$$\bar{\omega} = \frac{p_A + 1/2 \rho w_A^2 - (p_B + 1/2 \rho w_B^2)}{1/2 \rho w_A^2} \quad (1)$$

$$P_A = p_A + 1/2 \rho C_A^2 = p_A + 1/2 \rho (C_{x_A}^2 + C_{y_A}^2)$$

$$P_A = p_A + 1/2 \rho \left[C_{y_A}^2 + w_A^2 - w_{y_A}^2 \right]$$

$$P_A = p_A + 1/2 \rho \left[C_{y_A}^2 + w_A^2 - (U - C_{y_A})^2 \right]$$

Or:

$$1/2 \rho w_A^2 = P_A - p_A + \rho U \left(\frac{U}{2} - C_{y_A} \right)$$

Likewise:

$$1/2 \rho w_B^2 = P_B - p_B + \rho U \left(\frac{U}{2} - C_{y_B} \right)$$

Substituting (2) into (1):

$$\bar{\omega} = \frac{p_A - p_B + \left[[p_A - p_A + \rho U \left(\frac{U}{2} - C_{y_A} \right)] - [p_B - p_B + \rho U \left(\frac{U}{2} - C_{y_B} \right)] \right]}{p_A - p_A + \rho U \left(\frac{U}{2} - C_{y_A} \right)}$$

$$\bar{\omega} = \frac{p_A - p_B + \rho U (C_{y_B} - C_{y_A})}{p_A - p_A + \rho U \left(\frac{U}{2} - C_{y_A} \right)}$$

For stators, $U = 0$, therefore:

$$\bar{w} = \frac{P_0 - P_B}{P_A - P_A} = \frac{P_A - P_B}{1/2 \rho C_A^2} \quad (3)$$

This is the definition of absolute total pressure loss coefficient.

APPENDIX D

Source listing of the modified subroutine UD0307, which supplies UD03AR with enthalpy and entropy, appears below. Modifications are on lines 61 - 65, 69 - 72, 142 - 146, and 158 - 160.

```

1      SUBROUTINE UD0307
2      REAL LOSS,LAMI,LAMIP1,LAMIMI
3      COMMON NSTNS,NSTRMS,NMAX,NFORCE,NBL,NCASE,NSPLIT,NRFAD,NPUNCH,NPAGS$07$ 2
4      1E,NSET1,NSET2,ISTAG,ICASE,IFAIL0,IPASS,I,IVFAIL,IFFAIL,NMIX,NTRANS$07$ 3
5      2,NPLOT,ILOSS,LNCT,ITUB,IMID,IFAIL,ITER,LOG1,LOG2,LOG3,LOG4,LOG5,LOG6$07$ 4
6      3G6,IPRINT,NMANY,NSTPLT,NEQN
7      COMMON NSPEC(30),NWORK(30),NLOSS(30),NDATA(30),NTERP(30),NMACH(30),$07$ 5
8      1,NL1(30),NL2(30),NDIMEN(30),IS1(30),IS2(30),IS3(30),NEVAL(30),NDIFS$07$ 6
9      2F(4),NDFL(30),NLITER(30),NMH12,NRAD(2),NCURVE(30),NWHICH(30),NOUT1$07$ 7
10     3(30),NOUT2(30),NOUT3(30),NBLADE(30)
11     COMMON DM(11,5,2),WFRAC(11,5,2)
12     COMMON R(21,30),XL(21,30),X(21,30),H(21,30),S(21,30),VM(21,30),VW$07$ 8
13     121,30),TBETA(21,30),DIFF(15,4),EDHUE(15,4),EDMID(15,4),FDTRIP(15,4)$07$ 9
14     2,TERAD(5,2)
15     COMMON DATA1(100),DATA1(100),DATA2(100),DATA3(100),DATA4(100),DATA5$07$ 10
16     15(100),DATA6(100),DATA7(100),DATA8(100),DATA9(100),FLOW(10),SPEED$07$ 11
17     230),SPDFAC(10),BBLOCK(30),BDIST(30),WBLOCK(30),WWBL(30),XSTN(150),$07$ 12
18     3RSTN(150),DEL1(30),DEL2(100),DELTA(100),TITLE(18),ORDM2(30),RIM1(3$07$ 13
19     40),XIM1(30),WORK(21),LOSS(21),TANEPS(21),XI(21),VV(21),DELH(21),LA$07$ 14
20     SMI(21),LAMIM1(21),LAMIP1(21),PHI(21),CR(21),GAMA(21),SPPG(21),CPPG$07$ 15
21     6(21),HKEEP(21),SKEEP(21),VKEEP(21),DELH(30),DELT(30)
22     COMMON VISK,SHAPE,SCLFAC,EJ,G,TOLNCE,XSCALE,PSCALE,PLOW,RLOW,XMMAX$07$ 16
23     1,RCONST,FM2,HMIN,C1,PI,CONTR,CONMX
24     L1=I+NL1(I)
25     L2=I+NL2(I)
26     IW=NWORK(I)
27     IL=NLOSS(I)
28     XN=SPEED(I)*SPDFAC(ICASE)*PI/(30.0*SCLFAC)
29     GO TO(100,250,270,290,440,440),IW
30     100 GO TO(110,190,210,110),IL
31     110 IF(L2,NE,I)GO TO 150
32     DO 140 J=1,NSTRMS
33     IF(IPASS.EQ.1.AND.ITER.EQ.0)GO TO 120
34     IF(ITER.EQ.0)VW(J)=VM(J,I)
35     X1=H(J,I)-(VW(J)**2+VW(J,I)**2)/(2.0*G*EJ)
36     X2=H(J,I)-(VW(J,I)**2-(VW(J,I)-XN*R(J,I))**2)/(2.0*G*EJ)
37     IF(X1.LT.HMIN)X1=HMIN
38     IF(X2.LT.HMIN)X2=HMIN
39     X3=1.0/(1.0+LOSS(J)*(1.0-UDG4(X1,S(J,I))/UDG4(X2,S(J,I))))$07$ 17
40     GO TO 130
41     120 X3=1.0
42     130 H(J,I)=UDG2(S(J,L1),WORK(J)/X3)
43     140 S(J,I)=UD63(WORK(J),H(J,I))
44     GO TO 230
45     150 DO 180 J=1,NSTRMS
46     IF(IPASS.EQ.1.AND.L2.GT.I)GO TO 160
47     X1=H(J,L1)-(VW(J,L1)**2-(VW(J,L1)-XN*R(J,L1))**2)/(2.0*G*EJ)+XN**2$07$ 18
48     1*(R(J,I)**2-R(J,L1)**2)/(2.0*G*EJ)
49     IF(X1.LT.HMIN)X1=HMIN
50     X2=H(J,L2)-(VW(J,L2)**2+VW(J,L2)**2)/(2.0*G*EJ)
51     X3=H(J,L2)-(VW(J,L2)**2-(VW(J,L2)-XN*R(J,L2))**2)/(2.0*G*EJ)$07$ 19
52     IF(X2.LT.HMIN)X2=HMIN
53     IF(X3.LT.HMIN)X3=HMIN
54     X4=1.0-LOSS(J)/UD64(X1,S(J,L1))*(UD64(X3,S(J,L2))-UD64(X2,S(J,L2)))$07$ 20
55     11
56     GO TO 170

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57      160 X4=1.0          S075 58
58      170 H(J,I)=UDG2(S(J,L1),WORK(J)/X4)    S075 59
59      180 S(J,I)=UDG3(WORK(J),H(J,I))        S075 60
60      GO TO 230           S075 61
61      190 KTEMP=0         MOD.-JGW
62      DO 192 J=1,NSTRMS  MOD.-JGW
63      192 IF(ABS(LOSS(J)).GT.1.0) KTEMP=KTEMP+1  MOD.-JGW
64      IF(IEMP.EQ.NSTRMS) GO TO 205            MOD.-JGW
65      DO 200 J=1,NSTRMS  MOD.-JGW
66      H(J,I)=H(J,L1)+(UDG2(S(J,L1),WORK(J))-H(J,L1))/LOSS(J)  S075 63
67      200 S(J,I)=UDG3(WORK(J),H(J,I))        S075 64
68      GO TO 230           S075 65
69      205 DO 207 J=1,NSTRMS  MOD.-JGW
70      H(J,I)=UDG3(WORK(J),LOSS(J))        MOD.-JGW
71      207 S(J,I)=UDG3(WORK(J),H(J,I))        MOD.-JGW
72      GO TO 230           MOD.-JGW
73      210 DO 220 J=1,NSTRMS  S075 66
74      S(J,I)=S(J,L1)+LOSS(J)           S075 67
75      220 H(J,I)=UDG2(S(J,I),WORK(J))        S075 68
76      230 DO 240 J=1,NSTRMS  S075 69
77      240 VW(J,I)=(XN*RIM1(J)*VW(J,I-1)+(H(J,I)-H(J,I-1))*6*EJ)/(XN*R(J,I))  S075 70
78      GO TO 570           S075 71
79      250 DO 260 J=1,NSTRMS  S075 72
80      H(J,I)=WORK(J)           S075 73
81      260 VW(J,I)=(XN*RIM1(J)*VW(J,I-1)+(H(J,I)-H(J,I-1))*6*EJ)/(XN*R(J,I))  S075 74
82      GO TO 330           S075 75
83      270 DO 280 J=1,NSTRMS  S075 76
84      280 VW(J,I)=WORK(J)/R(J,I)        S075 77
85      GO TO 310           S075 78
86      290 DO 300 J=1,NSTRMS  S075 79
87      300 VW(J,I)=WORK(J)           S075 80
88      310 DO 320 J=1,NSTRMS  S075 81
89      320 H(J,I)=H(J,I-1)+XN*(R(J,I)*VW(J,I)-RIM1(J)*VW(J,I-1))/(G*EJ)  S075 82
90      330 GO TO (340,400,420,340),IL  S075 83
91      340 IF(L2.NE.I1) GO TO 370           S075 84
92      DO 360 J=1,NSTRMS  S075 85
93      IF(IPASS.EQ.1.AND.ITER.EQ.0) GO TO 350  S075 86
94      IF(ITER.EQ.0)VW(J)=VM(J,I)           S075 87
95      X1=H(J,I)-(VW(J)**2+VW(J,I)**2)/(2.0*G*EJ)  S075 88
96      X2=H(J,I)-(VW(J,I)**2-(VW(J,I)-XN*R(J,I))**2)/(2.0*G*EJ)  S075 89
97      IF(X1.LT.HMIN)X1=HMIN           S075 90
98      IF(X2.LT.HMIN)X2=HMIN           S075 91
99      X3=(1.0/(1.0+LOSS(J)*(1.0-UDG4(X1,S(J,I))/UDG4(X2,S(J,I)))))  S075 92
100     GO TO 360           S075 93
101     31 X3=1.0           S075 94
102     3 S(J,I)=UDG3(X3*UDG4(H(J,I),S(J,L1)),H(J,I))  S075 95
103     GO TO 570           S075 96
104     370 DO 390 J=1,NSTRMS  S075 97
105     IF(IPASS.EQ.1.AND.L2.GT.I) GO TO 380  S075 98
106     X1=H(J,L1)-(VW(J,L1)**2-(VW(J,L1)-XN*R(J,L1))**2)/(2.0*G*EJ)+XN**2  S075 99
107     I*(R(J,I)**2-R(J,L1)**2)/(2.0*G*EJ)           S075 100
108     IF(X1.LT.HMIN)X1=HMIN           S075 101
109     X2=H(J,L2)-(VM(J,L2)**2+VW(J,L2)**2)/(2.0*G*EJ)  S075 102
110     X3=H(J,L2)-(VW(J,L2)**2-(VW(J,L2)-XN*R(J,L2))**2)/(2.0*G*EJ)  S075 103
111     IF(X2.LT.HMIN)X2=HMIN           S075 104
112     IF(X3.LT.HMIN)X3=HMIN           S075 105
113     X4=1.0-LOSS(J)/UDG4(X1,S(J,L1))+UDG4(X2,S(J,L2))  S075 106

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```

114      1)                               $07$ 107
115      GO TO 390                      $07$ 108
116      380 X4=1.0                      $07$ 109
117      390 S(J,I)=UDG3(X4*UDG4(H(J,I),S(J,L1)),H(J,I)) $07$ 110
118      GO TO 570                      $07$ 111
119      400 DO 410 J=1,NSTRMS          $07$ 112
120      410 S(J,I)=UDG3(UDG4(H(J,L1)+LOSS(J)*(H(J,I)-H(J,L1)),S(J,L1)),H(J,I)) $07$ 113
121      GO TO 570                      $07$ 114
122      420 DO 430 J=1,NSTRMS          $07$ 115
123      430 S(J,I)=S(J,L1)+LOSS(J)    $07$ 116
124      GO TO 570                      $07$ 117
125      440 DO 450 J=1,NSTRMS          $07$ 118
126      450 XI(J)=H(J,I-1)-XN*RIM1(J)*VV(J,I-1)/(G*EJ) $07$ 119
127      GO TO(460,510,550,460),IL     $07$ 120
128      460 IF(L2.NE.I)GO TO 490      $07$ 121
129      DO 480 J=1,NSTRMS          $07$ 122
130      X2=XI(J)+(XN*R(J,I))**2/(2.0*G*EJ)      11/01/77
131      IF(IPASS.EQ.1.AND.ITER.EQ.0)GO TO 470      $07$ 123
132      IF(ITER.EQ.0)VV(J)=VM(J,I)                $07$ 124
133      C ....DELETE THIS STATEMENT....UPDATE: 11/01/77 $07$ 125
134      X1=X2-VV(J)**2/(1.0+TBETA(J,I)**2/(2.0*G*EJ)) $07$ 126
135      IF(X1.LT.HMIN)X1=HMIN                $07$ 127
136      IF(X2.LT.HMIN)X2=HMIN                $07$ 128
137      X3=1.0/(1.0+LOSS(J)*(1.0-UDG4(X1,S(I,I,I))/UDG4(X2,S(J,I)))) $07$ 129
138      GO TO 480                      $07$ 130
139      470 X3=1.0                      $07$ 131
140      480 S(J,I)=UDG3(X3*UDG4(X2,S(J,L1)),X2)      $07$ 132
141      GO TO 570                      $07$ 133
142      490 KPRES=0                    MOD.-JGW
143      DO 492 J=1,NSTRMS          MOD.-JGW
144      492 IF(ABS(LOSS(J)).GT.2.0)KPRES=KPRES+1      MOD.-JGW
145      IF(KPRES.EQ.NSTRMS)GO TO 505      MOD.-JGW
146      DO 500 J=1,NSTRMS          MOD.-JGW
147      X4=XI(J)+(XN*R(J,I))**2/(2.0*G*EJ)      $07$ 135
148      IF(X4.LT.HMIN)X4=HMIN                $07$ 136
149      X1=UDG4(X4,S(J,L1))                $07$ 137
150      IF(IPASS.EQ.1.AND.L2.GT.I)GO TO 500      $07$ 138
151      X2=XI(J)+(XN*R(J,L2))**2/(2.0*G*EJ)      $07$ 139
152      X3=H(J,L2)-(VM(J,L2)**2+VV(J,L2)**2)/(2.0*G*EJ) $07$ 140
153      IF(X2.LT.HMIN)X2=HMIN                $07$ 141
154      IF(X3.LT.HMIN)X3=HMIN                $07$ 142
155      X1=X1-LOSS(J)*(UDG4(X2,S(J,L2))-UDG4(X3,S(J,L2))) $07$ 143
156      500 S(J,I)=UDG3(X1,X4)            $07$ 144
157      GO TO 570                      $07$ 145
158      505 DO 506 J=1,NSTRMS          MOD.-JGW
159      506 S(J,I)=UDG3(LOSS(J),XI(J))      MOD.-JGW
160      GO TO 570                      MOD.-JGW
161      510 IF(IPASS.EQ.1.AND.ITER.EQ.0)GO TO 530      $07$ 146
162      DO 520 J=1,NSTRMS          $07$ 147
163      IF(ITER.EQ.0)VV(J)=VM(J,I)                $07$ 148
164      X1=H(J,I-1)+XN*(VV(J)*(TBETA(J,I)+XN*R(J,I)/VV(J))*R(J,I)-RIM1(J)*$07$ 149
165      IVW(J,I-1))/(G*EJ)                  $07$ 150
166      IF(X1.LT.HMIN)X1=HMIN                $07$ 151
167      X2=UDG4(H(J,L1)+(X1-H(J,L1))*LOSS(J),S(J,L1)) $07$ 152
168      520 S(J,I)=UDG3(X2,X1)            $07$ 153
169      GO TO 570                      $07$ 154
170      530 DO 540 J=1,NSTRMS          $07$ 155

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| | | | |
|-----|-----|------------------------|------------|
| 171 | 540 | S(J,I)=S(J,L1) | \$07\$ 156 |
| 172 | | GO TO 570 | \$07\$ 157 |
| 173 | 550 | DO 560 J=1,NSTRMS | \$07\$ 158 |
| 174 | 560 | S(J,I)=S(J,L1)+LOSS(J) | \$07\$ 159 |
| 175 | 570 | RETURN | \$07\$ 160 |
| 176 | | END | \$07\$ 161 |

Source listing of modified subroutine UD0302, the input routine, appears below. Modifications are on lines 190 - 198. Statement labels which indicate a date (line 177: 11/30/77) are program updates.

```

1      SUBROUTINE UD0302          $02$   2
2      REAL LOSS,LAMI,LAMIP1,LAMIM1          $02$   3
3      COMMON NSTNS,NSTRMS,NMAX,NFORCE,NBL,NCASE,NSPLIT,NREAD,NPUNCH,NPAGE$02$   4
4      1E,NSET1,NSET2,ISTAG,ICASE,IFAIL0,IPASS,I,IVFAIL,IFFAIL,NMIX,NTRANS$02$   5
5      2,NPLOT,ILOSS,LNCT,ITUB,IMID,IFAIL,ITER,LOG1,LOG2,LOG3,LOG4,LOG5,LOG$02$   6
6      3G6,IPRINT,NMANY,NSTPLT,NEQN          $02$   7
7      COMMON NSPEC(30),NWORK(30),NLoss(30),NDATA(30),INTERP(30),NMACH(30)$02$   8
8      1,NL1(30),NL2(30),NDIMEN(30),IS(30),I2(30),IS3(30),NEVAL(30),NDIF$02$   9
9      2F(4),NDEL(30),NLITER(30),NM(2),NAD(2),NCURVE(30),NWICH(30),NOUT$02$  10
10     3(30),NOUT2(30),NOUT3(30),NBLADE(30)          $02$  11
11     COMMON DM(11,5,2),WFR(11,5,2)          $02$  12
12     COMMON R(21,30),XL(21,30),X(21,30),H(21,30),S(21,30),VM(21,30),VW$02$  13
13     121,30),TBETA(21,30),DIFF(15,4),FDHUB(15,4),FDHIO(15,4),FDTIP(15,4)$02$  14
14     2,TERAD(S,2)          $02$  15
15     COMMON DATA1(100),DATA1(100),DATA2(100),DATA3(100),DATA4(100),DATAS$02$  16
16     15(100),DATA6(100),DATA7(100),DATA8(100),DATA9(100),FLOW(10),SPEED($02$  17
17     230),SPDFAC(10),BLOCK(30),BDIST(30),BLOCK(30),WWBL(30),XSTN(150),$02$  18
18     3RSTN(150),DELF(30),DELC(100),DELT(100),TITLE(18),DRDM2(30),RIM1(3$02$  19
19     40),XIM1(30),WORK(21),LOSS(21),TANEPS(21),XI(21),VV(21),DELW(21),LA$02$  20
20     5MI(21),LAMIM1(21),LAMIP1(21),PHT(21),CR(21),GAMA(21),SPPG(21),CPPG$02$  21
21     6(21),HKEEP(21),SKEEP(21),VWEEP(21),DELH(30),DELT(30)          $02$  22
22     COMMON VISK,SHAPE,SCLFAC,EJ,G,TOLNCE,XSCALE,PSCALE,PLOW,RLOW,XMMAX$02$  23
23     1,RCONST,FP2,HMIN,C1,PI,CONTR,CONMX          $02$  24
24     DIMENSION II(21,30),JJ(21,30)          $02$  25
25     EQUIVALENCE (H,II),(S,JJ)          $02$  26
26     COMMON/PAGE/LIMIT,LQ          $02$  27
27     NEVAL(1)=0          $02$  28
28     READ(LOG1,100)TITLE          $02$  29
29     100 FORMAT(1SA4)          $02$  30
30     WRITE(LOG2,110)TITLE          $02$  31
31     110 FORMAT(10X,1CHINPUT DATA,/,10X,10(1H*),//,10X,5HTITLE,34X,2H=,18A$02$  32
32     14)          $02$  33
33     LNCT=LNCT+4          $02$  34
34     CALL UDGI(LNCT)          $02$  35
35     READ(LOG1,12G)NSTNS,NSTRMS,NMAX,NFORCE,NBL,NCASE,NSPLIT,NSET1,NSET$02$  36
36     12,NREAD,NPUNCH,NPLOT,NPAGE,NTRANS,NMIX,NMANY,NSTPLT,NEQN          $02$  37
37     120 FORMAT(18I3)          $02$  38
38     IF(NSTRMS.EQ.0)NSTRMS=11          $02$  39
39     IF(NMAX.EQ.0)NMAX=40          $02$  40
40     IF(NFORCE.EQ.0)NFORCE=10          $02$  41
41     IF(NCASE.EQ.0)NCASE=1          $02$  42
42     IF(NPAGE.EQ.0)NPAGE=80          $02$  43
43     LQ=LOG2          $02$  44
44     LIMIT=NPAGE          $02$  45
45     CALL UD0303(LNCT,19)          $02$  46
46     WRITE(LOG2,130)NSTNS,NSTRMS,NMAX,NFORCE,NBL,NCASE,NSPLIT,NSET1,NSE$02$  47
47     1T2,NREAD,NPUNCH,NPLOT,NPAGE,NTRANS,NMIX,NMANY,NSTPLT,NEQN          $02$  48
48     130 FORMAT(2X,/,10X,18HNUMBER OF STATIONS,21X,1H=,I3,/,10X,21HNUMBER $02$  49
49     1F STREAMLINES,18X,1H=,I3,/,10X,20HMAX NUMBER OF PASSES,19X,1H=,I3,$02$  50
50     2/,10X,30HMAX NUMBER OF ARBITRARY PASSES,9X,1H=,I3,/,10X,29HBOUNDAR$02$  51
51     3Y LAYER CALC INDICATOR,10X,1H=,I3,/,10X,24HNUMBER OF RUNNING POINT$02$  52
52     4S,15X,1H=,I3,/,10X,33HSTREAMLINE DISTRIBUTION INDICATOR,6X,1H=,I3,$02$  53
53     5/,10X,34HNUMBER OF LOSS/D-FACTOR CURVE SETS,5X,1H=,I3,/,10X,34HNUM$02$  54
54     6BER OF LOSS/T.E.LOSS CURVE SETS,5X,1H=,I3,/,10X,26HSTREAMLINE INPUT$02$  55
55     7T INDICATOR,13X,1H=,I3,/,10X,27HSTREAMLINE OUTPUT INDICATOR,12X,1H$02$  56
56     8=,I3,/,10X,24HPRECISION PLOT INDICATOR,15X,1H=,I3,/,10X,24HMAX NUM$02$  57

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57      9BER OF LINES/PAGE,15X,1H=,I3,/,10X,29HWAKE TRANSPORT CALC INDICATOR$02$ 58
58      AR,10X,1H=,I3,/,10X,32HMAINSTREAM MIXING CALC INDICATOR,7X,1H=,I3,/$02$ 59
59      B,10X,33HNO OF STATIONS FROM ANALYTIC SECTION,6X,1H=,I3,/,10X,27HLINE-$02$ 60
60      CPRINTER PLOT INDICATOR,12X,1H=,I3,/,10X,32HMOMENTUM EQUATION FORM $02$ 61
61      DINDICATOR,7X,1H=,I3) $02$ 62
62      ITUB=NSTRMS-1 $02$ 63
63      IMID=NSTRMS/2+1 $02$ 64
64      IF(NMANY.EQ.0)GO TO 136 $02$ 65
65      READ(LOG61,132)(NWHICH(I),I=1,NMANY) $02$ 66
66      132 FORMAT(24I3) $02$ 67
67      CALL UDC303(LNCT,2) $02$ 68
68      WRITE(LOG62,134)(NWHICH(I),I=1,NMANY) $02$ 69
69      134 FORMAT(2X,/,10X,51HGEOMETRY COMES FROM ANALYTIC SECTION FOR STATI0$02$ 70
70      1NS ,23I3) $02$ 71
71      136 CALL UDC303(LNCT,7) $02$ 72
72      READ(LOG61,140)EJ,SCLFAC,TOLNCE,VISK,SHAPE $02$ 73
73      140 FORMAT(6F12.0) $02$ 74
74      IF(EJ.EQ.0.0)EJ=32.174 $02$ 75
75      IF(EJ.EQ.0.0)EJ=778.16 $02$ 76
76      IF(SCLFAC.EQ.0.0)SCLFAC=12.0 $02$ 77
77      IF(TOLNCE.EQ.0.0)TOLNCE=0.001 $02$ 78
78      IF(VISK.EQ.0.0)VISK=0.00018 $02$ 79
79      IF(SHAPE.EQ.0.0)SHAPE=0.7 $02$ 80
80      WRITE(LOG62,150)EJ,SCLFAC,TOLNCE,VISK,SHAPE $02$ 81
81      150 FORMAT(2X,/,10X,22HGRAVITATIONAL CONSTANT,17X,1H=F8.4,/,10X,17HJ0$02$ 82
82      1ULES EQUIVALENT,22X,1H=F8.3,/,10X,29HLINEAR DIMENSION SCALE FACTOR$02$ 83
83      2R,10X,1H=F8.4,/,10X,15HBASIC TOLERANCE,24X,1H=F8.5,/,10X,19HKINES$02$ 84
84      3HATIC VISCOSITY,20X,1H=F8.5,/,10X,17HL,L, SHAPE FACTOR,22X,1H=F8$02$ 85
85      4.5) $02$ 86
86      CALL UDC303(LNCT,7) $02$ 87
87      READ(LOG61,140)XSCALE,PSCALE,RLOW,PLOW,XMMAX,RCONST $02$ 88
88      IF(XMMAX.EQ.0.0)XMMAX=0.6 $02$ 89
89      IF(RCONST.EQ.0.0)RCONST=6.0 $02$ 90
90      WRITE(LOG62,160)XSCALE,PSCALE,RLOW,PLOW,XMMAX,RCONST $02$ 91
91      160 FORMAT(2X,/,10X,29HPLOTTING SCALE FOR DIMENSIONS,10X,1H=F7.3,/,10$02$ 92
92      1X,28HPLOTTING SCALE FOR PRESSURES,11X,1H=F7.3,/,10X,22HMINIMUM RA$02$ 93
93      2DIUS ON PLOT,17X,1H=F7.3,/,10X,24HMINIMUM PRESSURE ON PLOT,15X,1H$02$ 94
94      3=F7.3,/,10X,40HMAXIMUM M-SQUARED IN RELAXATION FACTOR =,F8.4,/,10$02$ 95
95      4X,29HCONSTANT IN RELAXATION FACTOR,10X,1H=F8.4) $02$ 96
96      CALL UDC303(LNCT,3) $02$ 97
97      READ(LOG61,140)CONTR,CONMX $02$ 98
98      WRITE(LOG62,164)CONTR,CONMX $02$ 99
99      164 FORMAT(2X,/,10X,22HWAKE TRANSFER CONSTANT,17X,1H=F8.5,/,10X,25HTU$02$ 100
100     1RBULENT MIXING CONSTANT,14X,1H=F8.5) $02$ 101
101     CALL UDC303(LNCT,5+NCASE) $02$ 102
102     READ(LOG61,17C)(FLOW(K),SPDFAC(K),K=1,NCASE) $02$ 103
103     1 J FORMAT(2F12.0) $02$ 104
104     WRITE(LOG62,180)(K,FLOW(K),SPDFAC(K),K=1,NCASE) $02$ 105
105     180 FORMAT(2X,/,10X,21HPOINTS TO BE COMPUTED,/,10X,2HNO,6X,8HFLOWRATE$02$ 106
106     1,4X,12HSPEED FACTOR,/,,(10X,I2,F13.3,F14.3)) $02$ 107
107     READ(LOG61,190)L1,(XSTN(K),RSTN(K),K=1,L1) $02$ 108
108     190 FORMAT(I3,/,12F12.0)) $02$ 109
109     ISTAG=0 $02$ 110
110     IF(RSTN(1).EQ.0.0)ISTAG=1 $02$ 111
111     NSPEC(1)=L1 $02$ 112
112     CALL UDC303(LNCT,7+L1) $02$ 113
113     WRITE(LOG62,200)L1,(XSTN(K),RSTN(K),K=1,L1) $02$ 114

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114      200  FORMAT(2X,/10X,36HANNULUS / COMPUTING STATION GEOMETRY //,10X,24H$02$ 115
115      1STATION 1 SPECIFIED BY,I3,7H POINTS,/,17X,4HXSTN,8X,4HRSTN,/,,(S02$ 116
116      2F22.4,F12.4)) $02$ 117
117      IS1(I)=1 $02$ 118
118      LAST=L1 $02$ 119
119      DO 220 I=2,NSTNS $02$ 120
120      READ(L061,210),L1 $02$ 121
121      210  FORMAT(I3) $02$ 122
122      NEXT=LAST+1 $02$ 123
123      LAST=LAST+L1 $02$ 124
124      IF(LAST.GT.150)GO TO 550 $02$ 125
125      READ(L061,170)(XSTN(K),RSTN(K),K=NEXT,LAST) $02$ 126
126      IF(RSTN(NEXT).EQ.0.0)ISTAGE=I $02$ 127
127      CALL UDP303(LNCT,5+L1) $02$ 128
128      IS1(I)=NEXT $02$ 129
129      NSPEC(I)=L1 $02$ 130
130      220  WRITE(L062,230)I,L1,(XSTN(K),RSTN(K),K=NEXT,LAST) $02$ 131
131      230  FORMAT(2X,/10X,7HSTATION,I3,14H SPECIFIED BY,I3,7H POINTS,/,17X$02$ 132
132      1,4HXSTN,8X,4HRSTN,/,,(F22.4,F12.4)) $02$ 133
133      SPEED(1)=0.0 $02$ 134
134      READ(L061,240)L1,NTERP(1),NDIMEN(1),NMACH(1),(DATA1(K),DATA1(K),DAS$02$ 135
135      1TA2(K),DATA3(K),K=1,L1) $02$ 136
136      2 ,  FORMAT(4I3,/,(4F12.0)) $02$ 137
137      CALL UDP303(LNCT,7+L1) $02$ 138
138      IS2(I)=1 $02$ 139
139      NDATA(1)=L1 $02$ 140
140      LAST=L1 $02$ 141
141      WRITE(L062,250)L1,NTERP(1),NDIMEN(1),NMACH(1),(DATA1(K),DATA1(K),D$02$ 142
142      1ATA2(K),DATA3(K),K=1,L1) $02$ 143
143      250  FORMAT(2X,/10X,24HSTATION CALCULATION DATA,/,7X,18HSTATION 1 NS$02$ 144
144      1DATA=,I3,7H NTERP=,I2,8H NDIMEN=,I2,7H NMACH=,I2,/,11X,5HDATA,6X$02$ 145
145      2,14HTOTAL PRESSURE,4X,17HTOTAL TEMPERATURE,4X,11HHWIRL ANGLE,/,,(5$02$ 146
146      3X,F12.4,F15.4,F19.3,F18.3)) $02$ 147
147      DO 252 K=1,L1 $02$ 148
148      252  DATA1(K)=DATA1(K)*SCLFAC**2 $02$ 149
149      LAST=0 $02$ 150
150      NOUT1(I)=0 $02$ 151
151      NOUT2(I)=0 $02$ 152
152      DO 320 I=2,NSTNS $02$ 153
153      LOGN=L061 $02$ 154
154      IF(NMANY.EQ.0)GO TO 258 $02$ 155
155      DO 254 L1=1,NMANY $02$ 156
156      IF(NWHICH(L1)).EQ.I,GO TO 256 $02$ 157
157      254  CONTINUE $02$ 158
158      GO TO 258 $02$ 159
159      2 ,  LOGN=L065 $02$ 160
160      258  READ(LOGN,260)NDATA(I),NTERP(I),NDIMEN(I),NMACH(I),NW$02$ 161
161      1I),NL1(I),NL2(I),NEVAL(I),NCURVE(I),NLITER(I),NDEL(I),NOUT1(I),NOU$02$ 162
162      2T2(I),NOUT3(I),NBLADE(I) $02$ 163
163      260  FORMAT(16I3) $02$ 164
164      L1=3 $02$ 165
165      IF(NDATA(I).NE.0)L1=L1+5+NDATA(I) $02$ 166
166      IF(NDEL(I).NE.0)L1=L1+3+NDEL(I) $02$ 167
167      CALL UDP303(LNCT,L1) $02$ 168
168      WRITE(L062,270)I,NDATA(I),NTERP(I),NDIMEN(I),NMACH(I),NW$02$ 169
169      1SS(I),NL1(I),NL2(I),NEVAL(I),NCURVE(I),NLITER(I),NDEL(I),NOUT1(I),$02$ 170
170      2NOUT2(I),NOUT3(I),NBLADE(I) $02$ 171

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171      270  FORMAT(2X,/, 7X,7HSTATION,I3,8H NDATA=,I3,7H NTERP=,I2,8H NDIMEN=S02S 172
172      1,I2,7H NMACH=,I2,7H NWORKE=,I2,7H NLSS=,I2,5H NL1=,I3,5H NL2=,I3,7S02S 173
173      2H NEVAL=,I2,8H NCURVE=,I2,8H NLITER=,I3,6H NDEL=,I3,/,19X,6HNOUT1=S02S 174
174      3,I2,7H NOUT2=,I2,7H NOUT3=,I2,8H NBLADE=,I3I S02S 175
175      SPEED(I)=0.0 S02S 176
176      IF(NDATA(I).EQ.0)GO TO 320 S02S 177
177      IF(NWORK(I).EQ.7)NLOSS(I)=1 11/30/77
178      NEXT=LAST+1 S02S 178
179      LAST=LAST+NDATA(I) S02S 179
180      IS2(I)=NEXT S02S 180
181      IF(LAST.GT.100)GO TO 550 S02S 181
182      READ(LOGN,28C)SPEED(I),(DATA1(K),DATA2(K),DATA3(K),DATA4(S02S 182
183      1K),DATA5(K),DATA6(K),DATA7(K),DATA8(K),DATA9(K),K=NEXT,LAST) S02S 183
184      28C  FORMAT(F12.0,/, (6F12.0,/,4F12.0)) S02S 184
185      WRITE(LOG2,290)SPEED(I),(DATA1(K),DATA2(K),DATA3(K),DATA4(S02S 185
186      1K),DATA5(K),DATA6(K),DATA7(K),DATA8(K),DATA9(K),K=NEXT,LAST) S02S 186
187      290  FORMAT(2X,/,10X,7HSPEED =,F9.2,/,13X,5HDATA1,7X,5HDATA2,7X,5HDATA3,7X,5HDATA4,7X,5HDATA5,7X,5HDATA6,7X,5HDATA7,7X,5HDATA8) S02S 187
188      28,7X,5HDATA9,/,,(10X,F9.4,F12.3,F13.6,F11.4,F12.5,F12.5,4F12.4), S02S 188
189      IF(NLOSS(I).NE.1)GO TO 293 MOD.-JGW
190      IF(NLOSS(I).NE.1)GO TO 293 MOD.-JGW
191      KPRESS=0 MOD.-JGW
192      DO 291 K=NEXT,LAST MOD.-JGW
193      291 IF(ABS(DATA2(K)).GT.2.0)KPRESS=KPRESS+1 MOD.-JGW
194      KCHECK=LAST-NEXT+1 MOD.-JGW
195      IF(KPRESS.NE.KCHECK)GO TO 293 MOD.-JGW
196      DO 292 K=NEXT,LAST MOD.-JGW
197      292 DATA2(K)=DATA2(K)*SCLFAC**2 MOD.-JGW
198      293 IF(NWORK(I).NE.1)GO TO 296 MOD.-JGW
199      DO 294 K=NEXT,LAST S02S 191
200      294 DATA1(K)=DATA1(K)*SCLFAC**2 S02S 192
201      296 IF(NEVAL(I).GT.0.AND.NSTRMS.GT.NDATA(I))LAST=LAST+NSTRMS-NDATA(I) S02S 193
202      IF(NDEL(I).EQ.0)GO TO 320 S02S 194
203      NEXT=LASTD+1 S02S 195
204      LASTD=LASTD+NDEL(I) S02S 196
205      IS3(I)=NEXT S02S 197
206      IF(LASTD.GT.100)GO TO 550 S02S 198
207      READ(LOG1,300)(DELC(K),DELTA(K),K=NEXT,LASTD) S02S 199
208      300  FORMAT(2F12.0) S02S 200
209      WRITE(LO62,310)(DELC(K),DELTA(K),K=NEXT,LASTD) S02S 201
210      310  FORMAT(2X,/,13X,4HDEL,8X,5HDELTA,/,,(10X,F9.4,F12.4)) S02S 202
211      320  CONTINUE S02S 203
212      | CALL UDC303(LNCT,5+NSTNS) S02S 204
213      | READ(LOG1,330)(WBLOCK(I),BBLOCK(I),BDIST(I),I=1,NSTNS) S02S 205
214      3:   FORMAT(3F12.0) S02S 206
215      | WRITE(LO62,340)(I,WBLOCK(I),BBLOCK(I),BDIST(I),I=1,NSTNS) S02S 207
216      3 0  FORMAT(2X,/,10X,3CHBLOCKAGE FACTOR SPECIFICATIONS,/,10X,66HSTAT1) S02S 208
217      IN WALL BLOCKAGE WAKE BLOCKAGE WAKE DISTRIBUTION FACTOR,/,,(1S02S 209
218      23X,I4,F16.5,F16.5,F19.3) S02S 210
219      IF(NSET1.EQ.0)GO TO 380 S02S 211
220      DO 370 K=1,NSET1 S02S 212
221      READ(LOG1,350)L1,(DIFF(J,K),FDHUB(J,K),FDMID(J,K),FDTIP(J,K),J=1,L) S02S 213
222      11) S02S 214
223      350  FORMAT(I3,/, (4F12.0)) S02S 215
224      CALL UDO303(LNCT,6+L1) S02S 216
225      WRITE(LO62,360)K,L1,(DIFF(J,K),FDHUB(J,K),FDMID(J,K),FDTIP(J,K),J=1,L) S02S 217
226      11,L1) S02S 218
227      360  FORMAT(2X,/,10X,5SHLOSS PARAMETER / DIFFUSION FACTOR CURVES FOR BL502S 219

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228      1ADE TYPE,I2,I5,16H D-FACTORS GIVEN,//,15X,9HDIFFUSION,5X,3CHL 0 S $02$ 220
229      2S P A R A M E T E R S,//,16X,7HFACTORS,8.,3HHUB,9X,3HMTD,8X,3HTIPS$02$ 221
230      3.,//(15X,F8.3,F13.5,F12.5,F11.5)) $02$ 222
231      370 NDIFF(K)=L1 $02$ 223
232      380 IF(INSET2.EQ.0)GO TO 450 $02$ 224
233      DO 440 K=1,NSET2 $02$ 225
234      READ(LOG1,390)L1,L2 $02$ 226
235      390 FORMAT(2I3) $02$ 227
236      CALL UD0303(LNCT,7+L1) $02$ 228
237      NM(K)=L1 $02$ 229
238      NRAD(K)=L2 $02$ 230
239      RFAD(LOG1,400)TERAD(1,K),(DM(J,1,K),WFRAC(J,1,K),J=1,L1) $02$ 231
240      400 FORMAT(F12.0,/(2F12.0)) $02$ 232
241      WRITE(LOG2,410)K,L1,L2,TERAD(1,K),(DM(J,1,K),WFRAC(J,1,K),J=1,L1) $02$ 233
242      410 FORMAT(2X,/,10X,51HFRACTIONAL LOSS DISTRIBUTION CURVES FOR BLADE CS$02$ 234
243      1LASS,I2,I5,16H POINTS GIVEN AT,I3,17H RADIAL LOCATIONS,/,10X,52HFS$02$ 235
244      2RATION OF COMPUTING STATION LENGTH AT BLADE EXIT =,F7.4,/,10X,28$02$ 236
245      3HFRACTION OF MERIDIONAL CHORD,4X,26HLOSS/LOSS AT TRAILING EDGE,//,$02$ 237
246      *(15X,F11.4,2CX,F11.4)) $02$ 238
247      IF(L2.EQ.1)GO TO 440 $02$ 239
248      DO 420 L2=L2 $02$ 240
249      CALL UD0303(LNCT,5+L1) $02$ 241
250      READ(LOG1,400)TERAD(L,K),(DM(J,L,K),WFRAC(J,L,K),J=1,L1) $02$ 242
251      -20 WRITE(LOG2,430)TERAD(L,K),(DM(J,L,K),WFRAC(J,L,K),J=1,L1) $02$ 243
252      430 FORMAT(2X,/,10X,52HFRACTION OF COMPUTING STATION LENGTH AT BLADE ES$02$ 244
253      1XIT =,F7.4,/,10X,28HFRACTION OF MERIDIONAL CHORD,4X,26HLOSS/LOSS $02$ 245
254      2AT TRAILING EDGE,//,(15X,F11.4,20X,F11.4)) $02$ 246
255      440 CONTINUE $02$ 247
256      450 IF(NSPLIT.EQ.0.AND.NREAD.EQ.0)GO TO 570 $02$ 248
257      READ(061,460)(DELF(J),J=1,NSTRMS) $02$ 249
258      460 FORMAT(6F12.0) $02$ 250
259      L1=5 $02$ 251
260      IF(INSTRMS.GE.16)L1=8 $02$ 252
261      CALL UD0303(LNCT,L1) $02$ 253
262      WRITE(LOG2,470) $02$ 254
263      L1=NSTRMS $02$ 255
264      IF(INSTRMS.GT.15)L1=15 $02$ 256
265      WRITE(LOG2,480)(J,J=1,L1) $02$ 257
266      480 FORMAT(2X,/,10X,10HSTREAMLINE,I5,14I7) $02$ 258
267      470 FORMAT(2X,/,10X,78HPROPORTIONS OF TOTAL FLOW BETWEEN HUB AND EACH $02$ 259
268      1STREAMLINE ARE TO BE AS FOLLOWS) $02$ 260
269      WRITE(LOG2,490)(DELF(J),J=1,L1) $02$ 261
270      490 FORMAT(10X,4HFLOW,7X,1SF7.4) $02$ 262
271      IF(INSTRMS.LE.15)GO TO 500 $02$ 263
272      L1=L1+1 $02$ 264
273      WRITE(LOG2,480)(J,J=L1,NSTRMS) $02$ 265
274      WRITE(LOG2,490)(DELF(J),J=L1,NSTRMS) $02$ 266
275      500 IF(NREAD.EQ.0)GO TO 570 $02$ 267
276      READ(061,510)((R(J,I),X(J,I),XL(J,I),II(J,I),JJ(J,I),J=1,NSTRMS),$02$ 268
277      II=1,NSTNS) $02$ 269
278      510 FORMAT(3F12.0,2I3) $02$ 270
279      CALL UD0303(LNCT,5+NSTRMS) $02$ 271
280      WRITE(LOG2,520) $02$ 272
281      520 FORMAT(2X,/,10X,32HESTIMATED STREAMLINE COORDINATES) $02$ 273
282      DO 530 I=1,NSTNS $02$ 274
283      IF(I.GT.1)CALL UD0303(LNCT,3+NSTRMS) $02$ 275
284      530 WRITE(LOG2,540)(I,J,R(J,I),X(J,I),XL(J,I),II(J,I),JJ(J,I),J=1,NSTRMS$02$ 276

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| | | |
|-----|--|------------|
| 285 | 1MS) | \$02\$ 277 |
| 286 | 540 FORMAT(2X,/,10X,79HSTATION STREAMLINE RADIUS AXIAL COORDINATE | \$02\$ 278 |
| 287 | 1 L-COORDINATE CHECKS- I J, //, (3X,2I11,F14.4,F12.4,F16.4,I17\$02\$ 279 | |
| 288 | 2,I5)) | \$02\$ 280 |
| 289 | GO TO 570 | \$02\$ 281 |
| 290 | 550 WRITE(LOG2,560) | \$02\$ 282 |
| 291 | 560 FORMAT(1H1,10X,33HJOB STOPPED - TOO MUCH INPUT DATA) | \$02\$ 283 |
| 292 | STOP | \$02\$ 284 |
| 293 | 570 RETURN | \$02\$ 285 |
| 294 | END | \$02\$ 286 |

Source listing of the 1964 - 65 Version 5 CALCOMP subroutine, UDO312, appears below.

```

1      SUBROUTINE UDO312          $12$   2
2      REAL LOSS,LAMI,LAMIP1,LAMIM1          $12$   3
3      COMMON NSTNS,NSTRMS,NMAX,NFORCE,NBL,NCASE,NSPLIT,NREAD,NPUNCH,NPAGS$12$   4
4      1E+NSET1,NSET2,ISTAG,ICASE,IFAIL0,IPASS,I,IVFAIL,IFFAIL,NMIX,NTRANS$12$   5
5      2,NPLOT,ILLOSS,LNCT,ITUR,IMID,IFATL,ITER,LOG1,LOG2,LOG3,LOG4,LOG5,LOG$12$   6
6      3G6,IPRINT,NMANY,NSTPLT,NEON          $12$   7
7      COMMON NSPEC(30),NWORK(30),NLOSS(30),NDATA(30),NTERP(30),NMACH(30)$12$   8
8      1,NL1(30),NL2(30),NDIMEN(30),IS1(30),IS2(30),IS3(30),NEVAL(30),NDIFS$12$   9
9      2F(4),NDEL(30),NLITER(30),NM(2),VRAD(2),NCURVE(30),NWICH(30),NOUT$12$  10
10     3(30),NOUT2(30),NOUT3(30),NBLADE(30)          $12$  11
11     COMMON DM(11,5,2)-WFRAC(11,5,2)          $12$  12
12     COMMON R(21,30),XL(21,30),X(21,30),H(21,30),S(21,30),VM(21,30),VW$12$  13
13     121,30),TBETA(21,30),DIFF(15,4),FDHUB(15,4),FDMID(15,4),FDTIP(15,4)$12$  14
14     2,TERAD(5,2)          $12$  15
15     COMMON DATA1(100),DATA1(100),DATA2(100),DATA3(100),DATA4(100),DATAS$12$  16
16     15(100),DATA6(100),DATA7(100),DATA8(100),DATA9(100),FLOW(10),SPEED$12$  17
17     230),SPDFAC(10),RELOCK(30),BDIST(30),WPLOCK(30),WWBL(30),XTIN(150),$12$  18
18     2RSTN(150),DELF(30),DELC(100),DELTA(100),TITLE(18),DRDM2(30),RIM1(38)$12$  19
19     40),XIM1(3C),WORK(21),LOSS(21),TANEPS(21),XI(21),VV(21),DELW(21),AS$12$  20
20     5MI(21),LAMIM1(21),LAMIP1(21),PHI(21),CR(21),GAMA(21),SPPG(21),CPPG$12$  21
21     6(21),HKEEP(21),SKFP(21),VW(EEP(21),DELH(30),DELT(3C)          $12$  22
22     COMMON VISK,SHAPE,SCLFAC,EJ,G,TOLNCE,XSCALE,PSCALE,PLOW,RLOW,XMMAX$12$  23
23     1,RCONST,FM2,HMIN,C1,PI,CONTR,CONMX          $12$  24
24     DIMENSION PSTAT(32),XX(32)          $12$  25
25     XMAX=X(1,NSTNS)          $12$  26
26     XMIN=X(1,1)          $12$  27
27     DO 100 J=2,NSTRMS          $12$  28
28     IF(X(J,1).LT.XMIN)XMIN=X(J,1)          $12$  29
29     IF(X(J,NSTNS).GT.XMAX)XMAX=X(J,NSTNS)          $12$  30
30     100 CONTINUE          $12$  31
31     XMIN=FLOAT(IFIX(XMIN))          MOD.-JGW
32     IF((XMIN.GE.0.0).AND.(XMIN.LE.5.0))XMIN=0.0          MOD.-JGW
33     ALEN=(XMAX-XMIN)/XSCALE          MOD.-JGW
34     XLEN=20.0          MOD.-JGW
35     IF(ALEN.LE.10.0)XLEN=10.0          MOD.-JGW
36     IF(NPLOT.EQ.2)GO TO 134          $12$  42
37     CALL PLOTID          MOD.-JGW
38     CALL PLOT(0.0,-12.0,-3)          MOD.-JGW
39     CALL PLOT(0.0,0.5,-3)          MOD.-JGW
40     CALL AXIS(0.0,0.0,16HAXIAL COORDINATE,-16,XLEN,0.0,XMIN,XSCALE,10.0)MOD.-JGW
41     101          MOD.-JGW
42     CALL AXIS(0.0,0.0,15HSTATIC PRESSURE,15,10.0,90.0,PLOW,PSCALE,10.0)MOD.-JGW
43     11          MOD.-JGW
44     J=1          $12$  47
45     K=1          $12$  48
46     YPEN=3.4          MOD.-JGW
47     XPEN=(XMAX/XSCALE)-3.0          MOD.-JGW
48     SIZE=0.14          MOD.-JGW
49     110 DO 120 I=1,NSTNS          $12$  49
50     HS=H(J,I)-(VV(J,I)**2+VM(J,I)**2)/(2.0*E*EJ)          $12$  50
51     IF(HS.LT.HMIN)HS=HMIN          $12$  51
52     PSTAT(I)=UDG4(HS,S(J,I))/SCLFAC**2          $12$  52
53     120 XX(I)=X(J,I)          $12$  53
54     CALL LINE(XX,PSTAT,NSTNS,I,1,K,XMIN,XSCALE,PLOW,PSCALE)          MOD.-JGW
55     CALL SYMBOL(XPEN,YPEN+0.07,SIZE,K,0.0,-1)          MOD.-JGW
56     IF(J.EQ.NSTRMS)CALL SYMBOL(XPEN+0.14,YPEN,SIZE,17H=> TIP STREAMLIN)MOD.-JGW

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| | | |
|----|--|-----------|
| 57 | 1E,0.0,17) | MOD.-JGW |
| 58 | IF(J.EQ.NSTRMS)GO TO 130 | \$12\$ 55 |
| 59 | K=K+1 | \$12\$ 56 |
| 60 | IF(J.EQ.IMID)J=NSTRMS | \$12\$ 57 |
| 61 | IF(J.EQ.NSTRMS)CALL SYMBOL(XPEN+0.14,YPEN,SIZE,17H=> MID STREAMLINMOD.-JGW | |
| 62 | 1E,0.0,17) | MOD.-JGW |
| 63 | IF(J.EQ.1)J=IMID | \$12\$ 58 |
| 64 | IF(J.EQ.IMID)CALL SYMBOL(XPEN+0.14,YPEN,SIZE,17H=> HUB STREAMLINE,MOD.-JGW | |
| 65 | 10.0,17) | MOD.-JGW |
| 66 | YPEN=YPEN-0.25 | MOD.-JGW |
| 67 | GO TO 110 | \$12\$ 59 |
| 68 | 130 CALL PLOT(25.0,-12.0,-3) | MOD.-JGW |
| 69 | IF(NPLOT.EQ.1)GO TO 180 | \$12\$ 62 |
| 70 | 134 CALL PLOT1D | MOD.-JGW |
| 71 | CALL PLOT(0.0,-12.0,-3) | MOD.-JGW |
| 72 | CALL PLOT(0.0,0.5,-3) | MOD.-JGW |
| 73 | CALL AXIS(0.0,0.0,16HAXIAL COORDINATE,-16,XLEN,0.0,XMIN,XSCALE,10.0)MOD.-JGW | |
| 74 | 10) | MOD.-JGW |
| 75 | CALL AXIS(0.0,0.0,6HRADIUS,6,10.0,90.0,RLOW,XSCALE,10.0) | MOD.-JGW |
| 76 | DO 150 J=1,NSTRMS | \$12\$ 67 |
| 77 | DO 140 I=1,NSTNS | \$12\$ 68 |
| 78 | XX(I)=X(J,I) | \$12\$ 69 |
| 79 | 140 PSTAT(I)=R(J,I) | \$12\$ 70 |
| 80 | 150 CALL LINE(XX,PSTAT,NSTNS,1,0,11,XMIN,XSCALE,RLOW,XSCALE) | MOD.-JGW |
| 81 | DO 170 I=1,NSTNS | \$12\$ 76 |
| 82 | DO 160 J=1,NSTRMS | \$12\$ 77 |
| 83 | PSTAT(J)=R(J,I) | \$12\$ 78 |
| 84 | 160 XX(J)=X(J,I) | \$12\$ 79 |
| 85 | 170 CALL LINE(XX,PSTAT,NSTRMS,1,0,11,XMIN,XSCALE,RLOW,XSCALE) | MOD.-JGW |
| 86 | CALL PLOT(25.0,-12.0,-3) | MOD.-JGW |
| 87 | 180 CALL ENDCC | MOD.-JGW |
| 88 | RETURN | MOD.-JGW |
| 89 | END | \$12\$ 83 |

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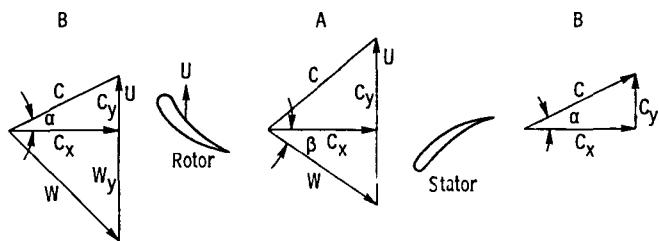


Figure 1 - Two-dimensional velocity triangles for an axial compressor.

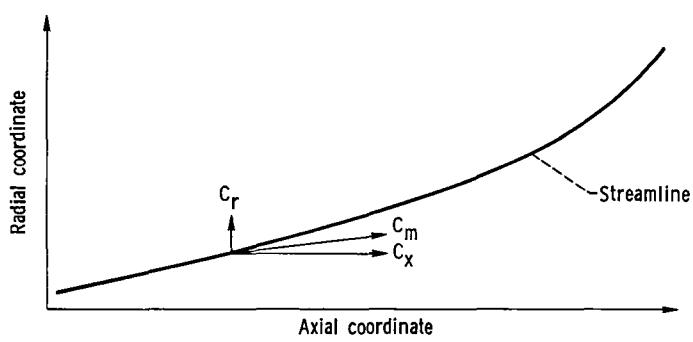


Figure 2 - Definition of meridional direction.

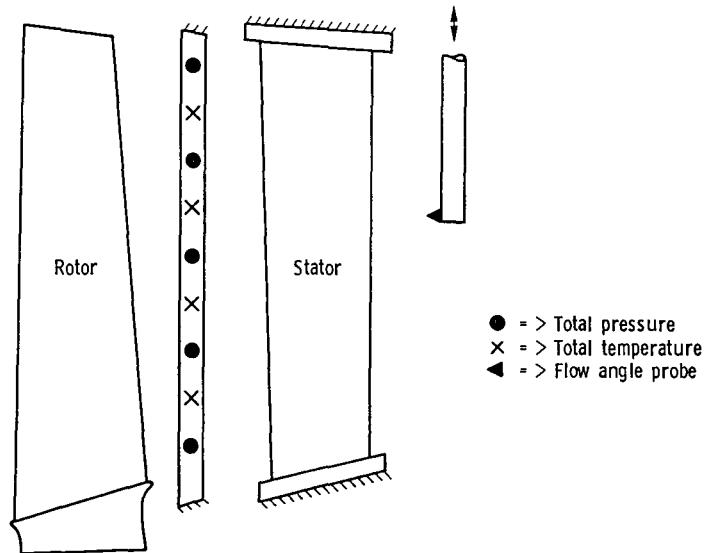


Figure 3. - Typical cascade instrumentation. The flow angle probe is capable of traversing radially. Total pressure may be obtained from flow angle probe.

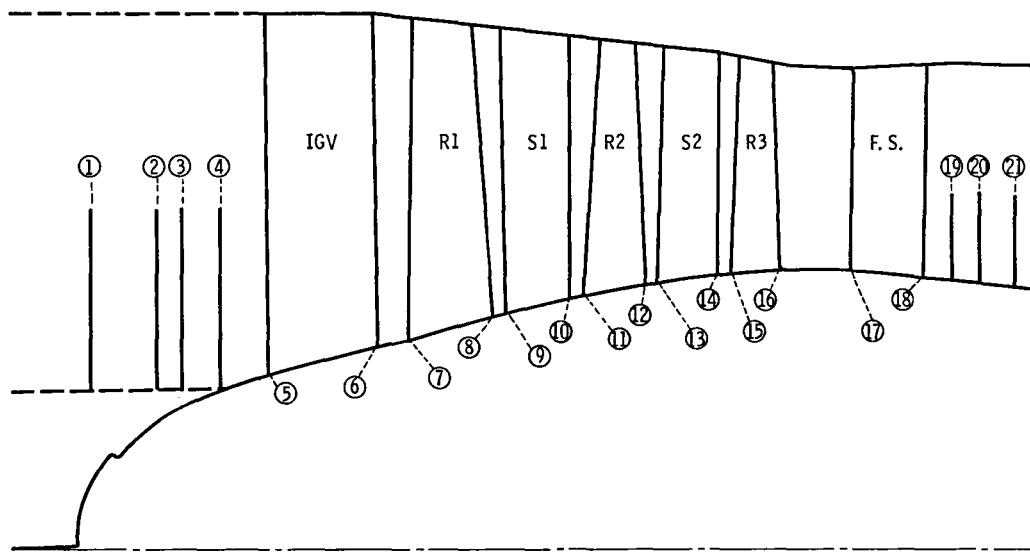


Figure 4. - Fan module axial station locations.

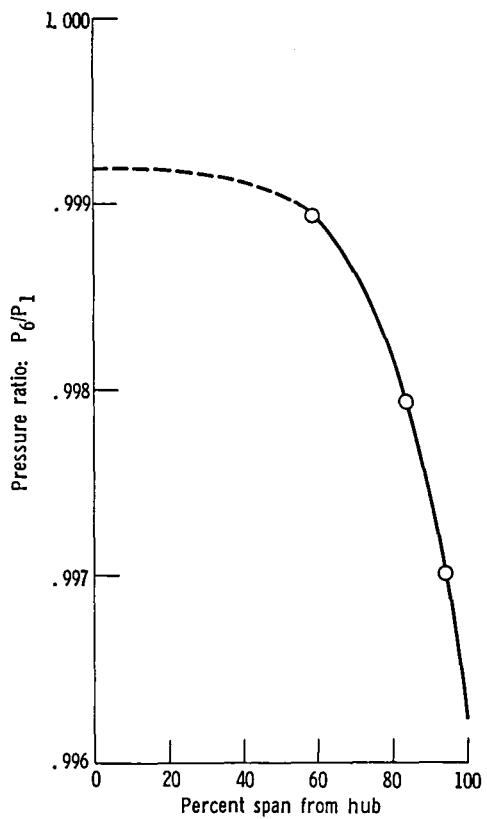


Figure 5. - Total pressure profile behind Inlet Guide Vane (Station 6). Data comes from flow angle probe. $P_1 = 136,907 \text{ kPa}$ (19.856 psia).

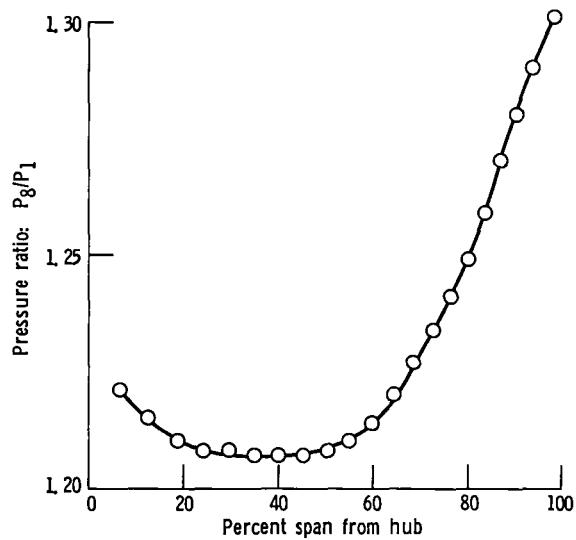


Figure 6. - Total pressure profile behind first rotor (Station 8). $P_1 = 136,907 \text{ kPa}$ (19.856 psia).

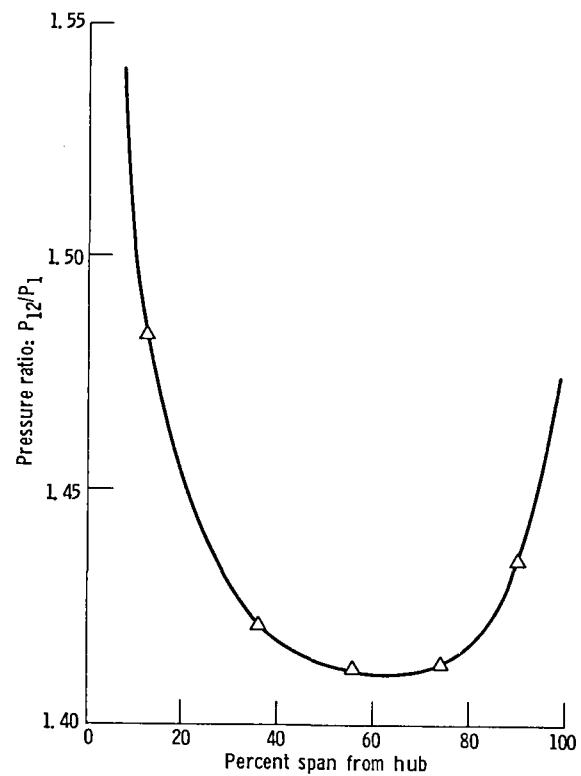


Figure 7. - Total pressure profile behind second rotor
(Station 12). $P_1 = 136.907 \text{ kPa}$ (19.856 psia).

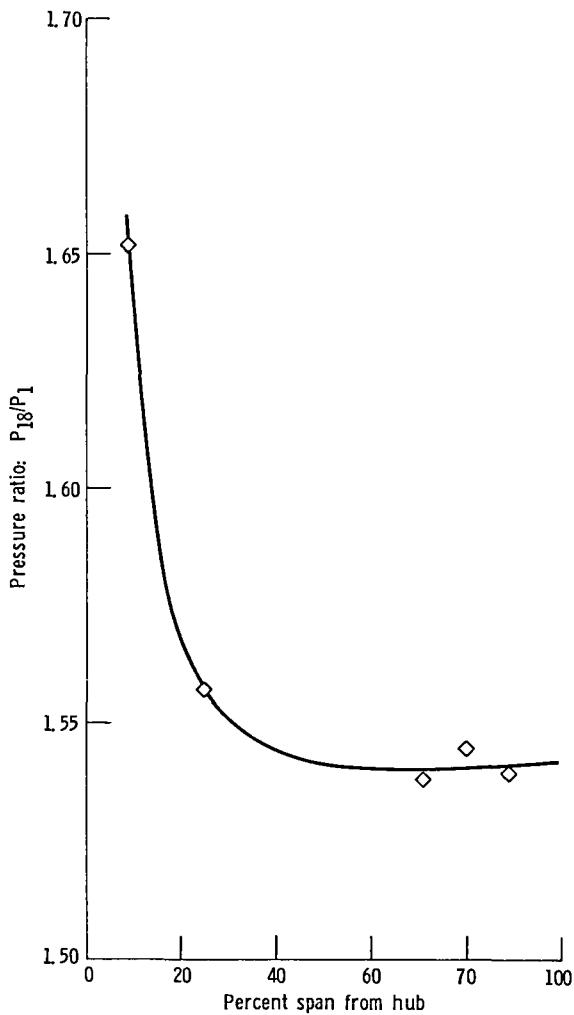


Figure 8. - Total pressure profile behind flow straightener
(Station 18). $P_1 = 136.907 \text{ kPa}$ (19.856 psia).

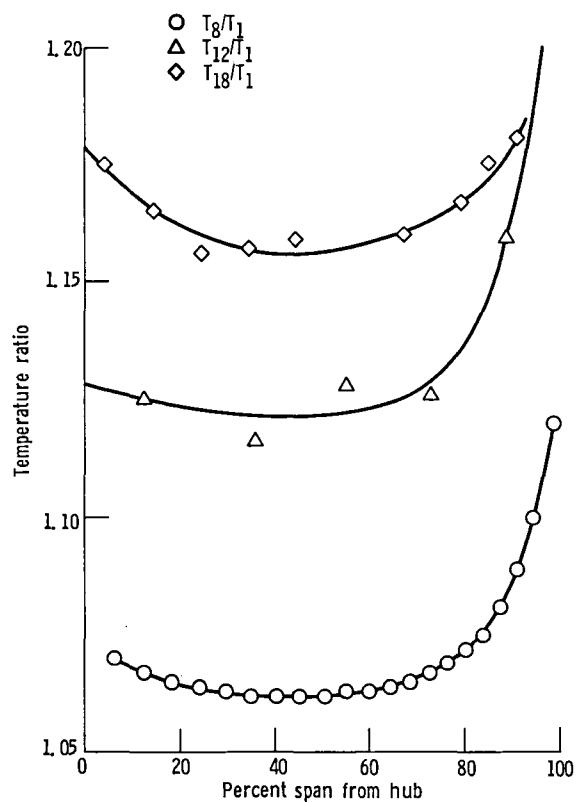
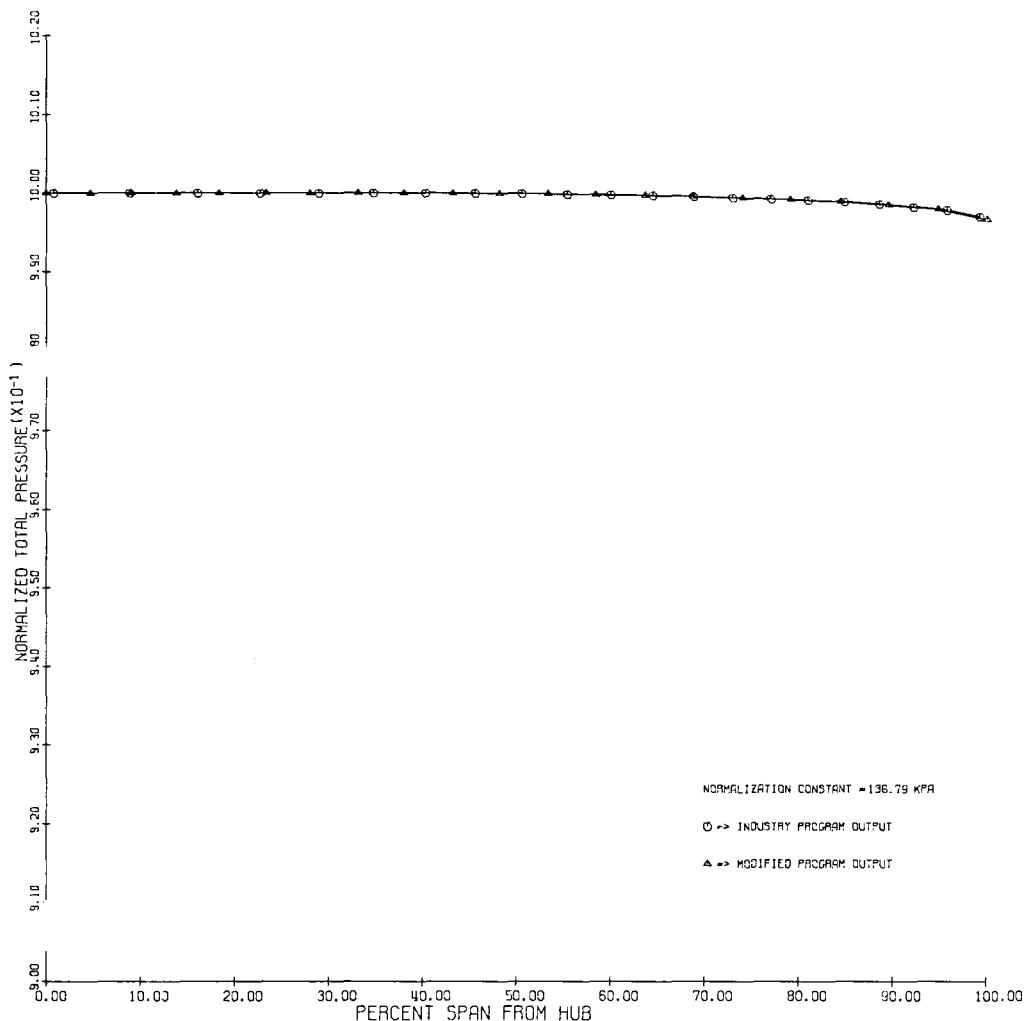
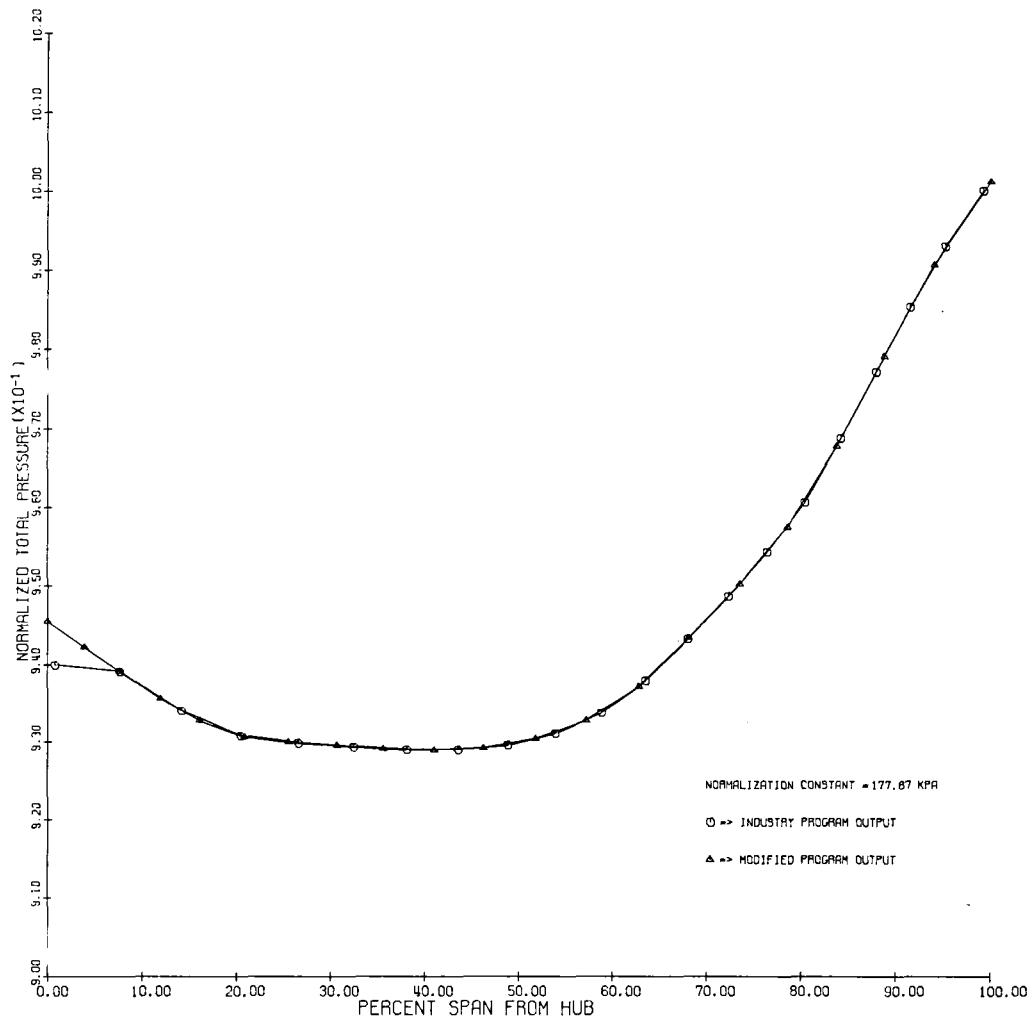


Figure 9. - Temperature profiles at axial stations.
 $T_1 = 442.82\text{K}$ (797.08R).



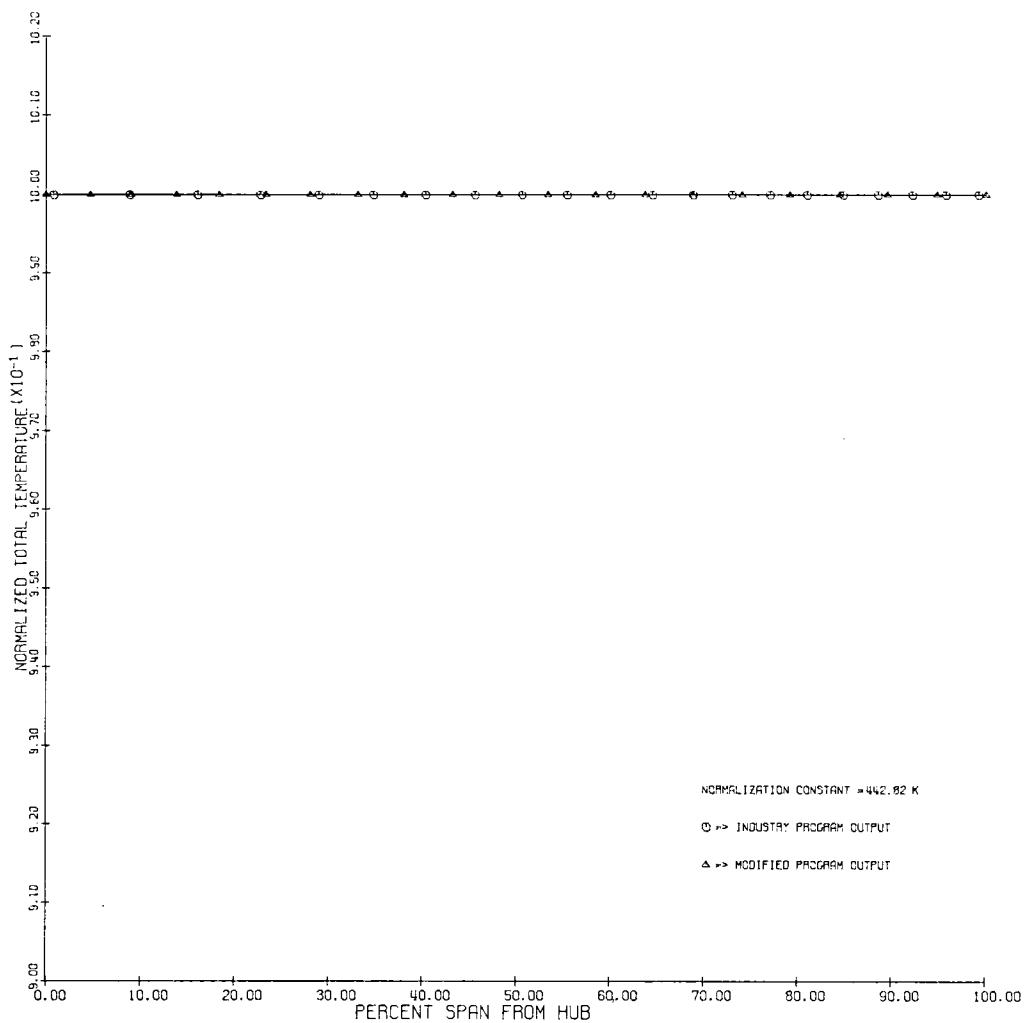
(a) Station 7.

Figure 10. - Comparison of program total pressure output.



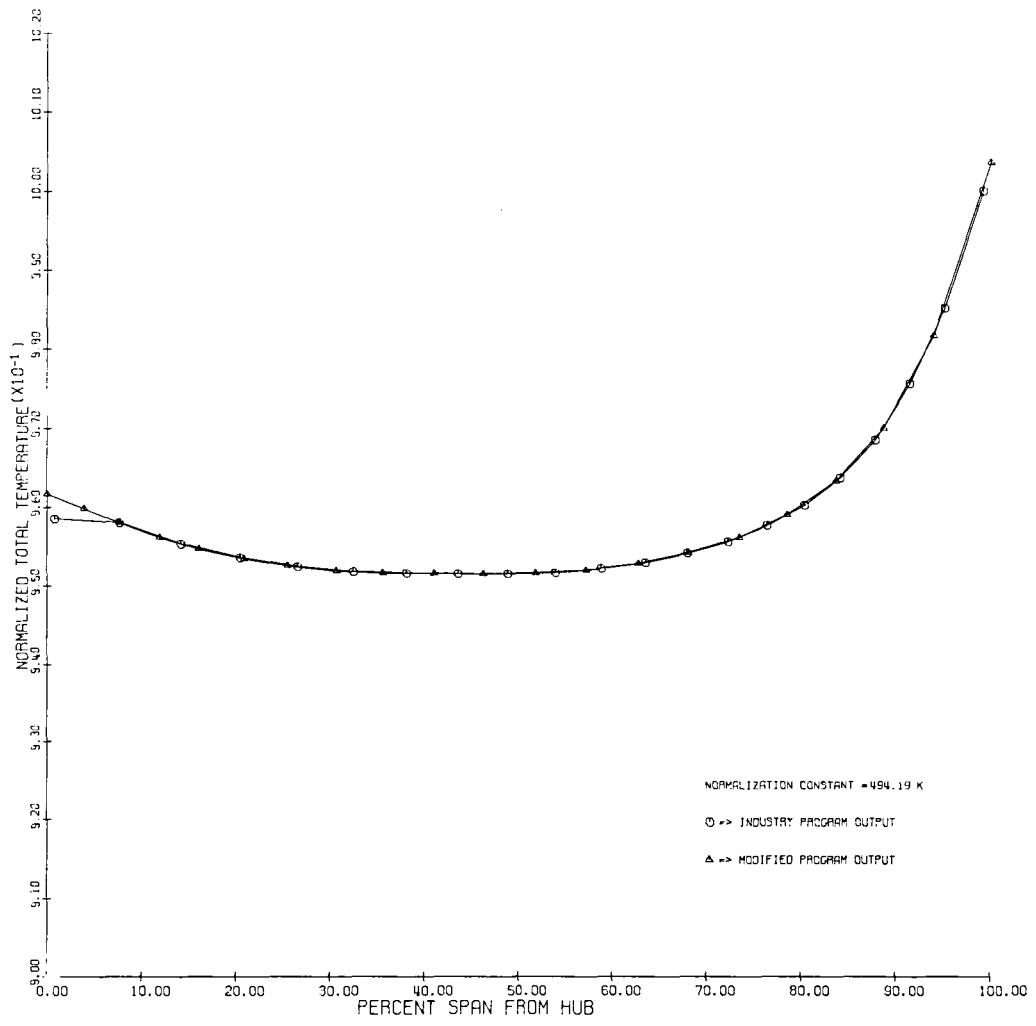
(b) Station 8.

Figure 10a - Concluded.



(a) Station 7.

Figure 11. - Comparison of program total temperature output.



(b) Station 8.

Figure 11. - Concluded.

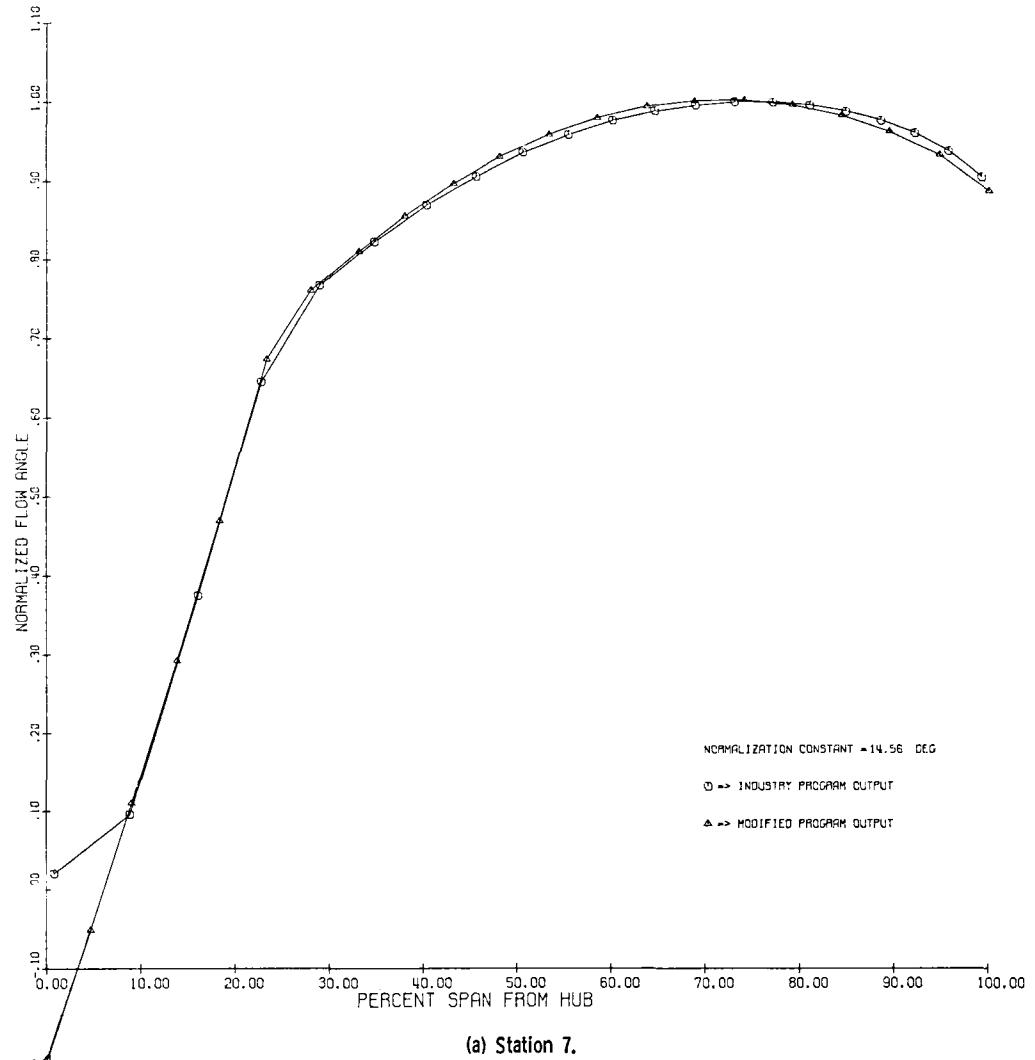
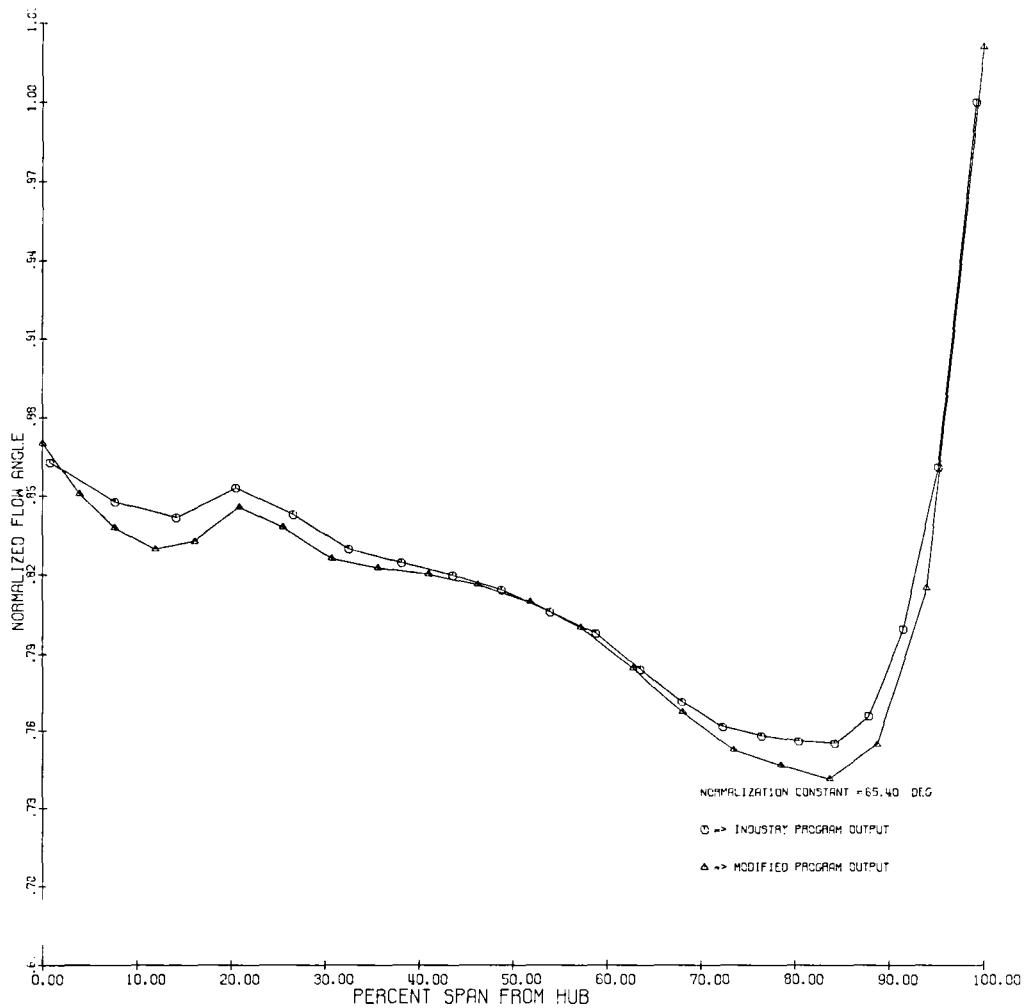


Figure 12. - Comparison of program flow angle output



(b) Station 8.

Figure 12 - Concluded.

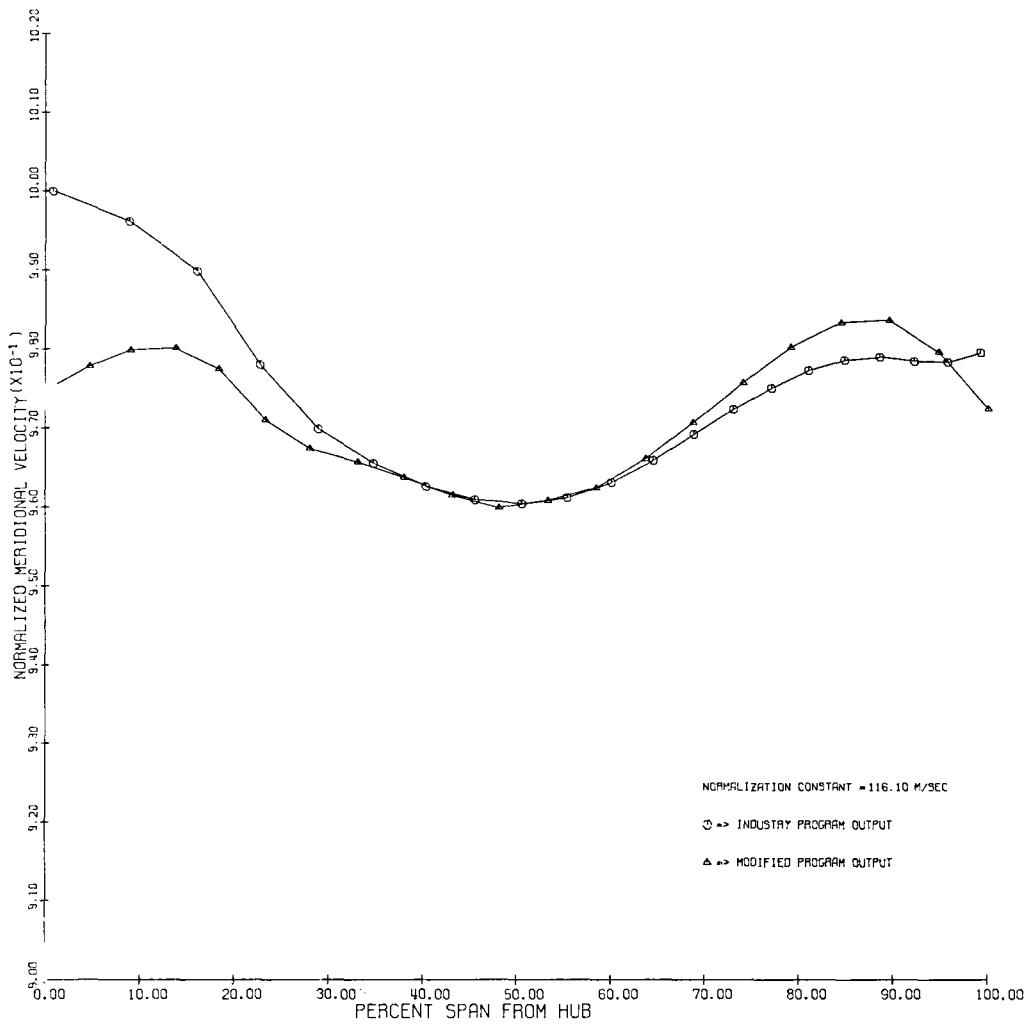
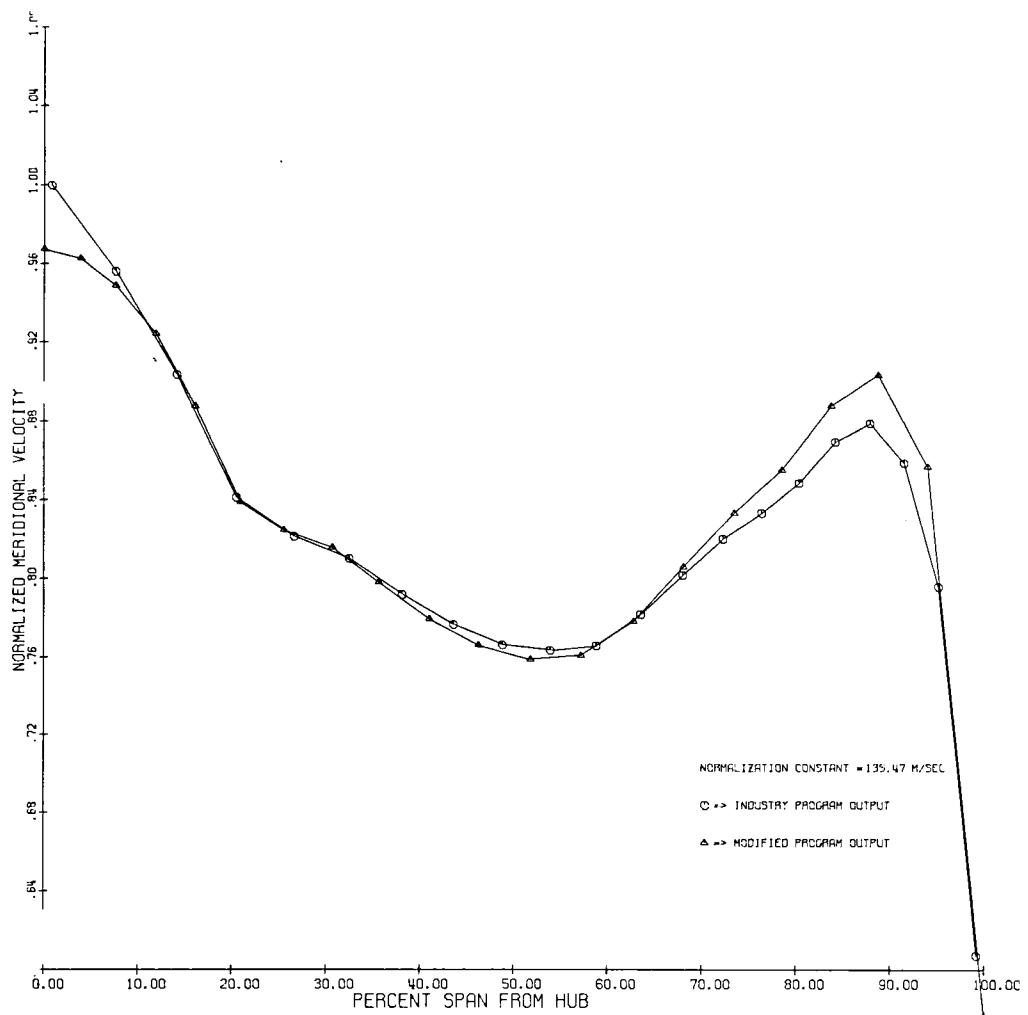
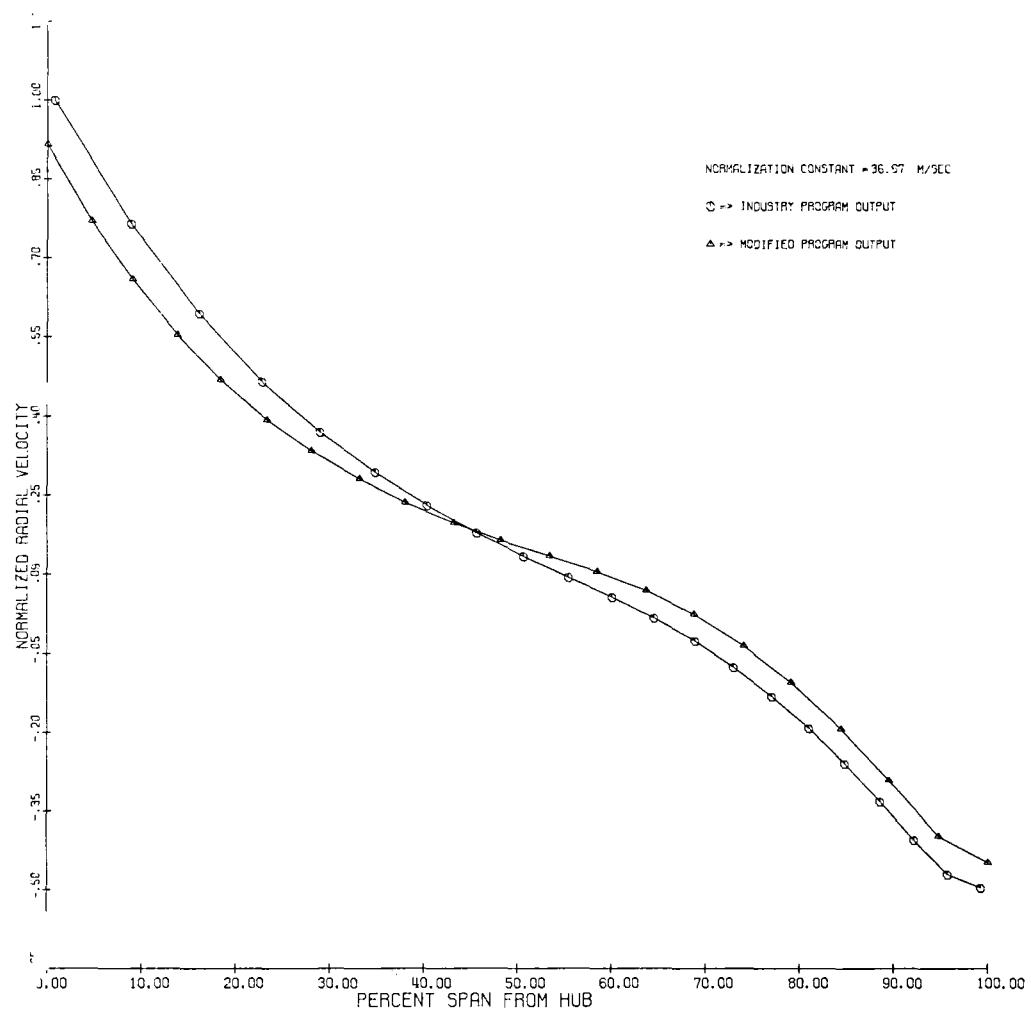


Figure 13. - Comparison of program meridional velocity output.



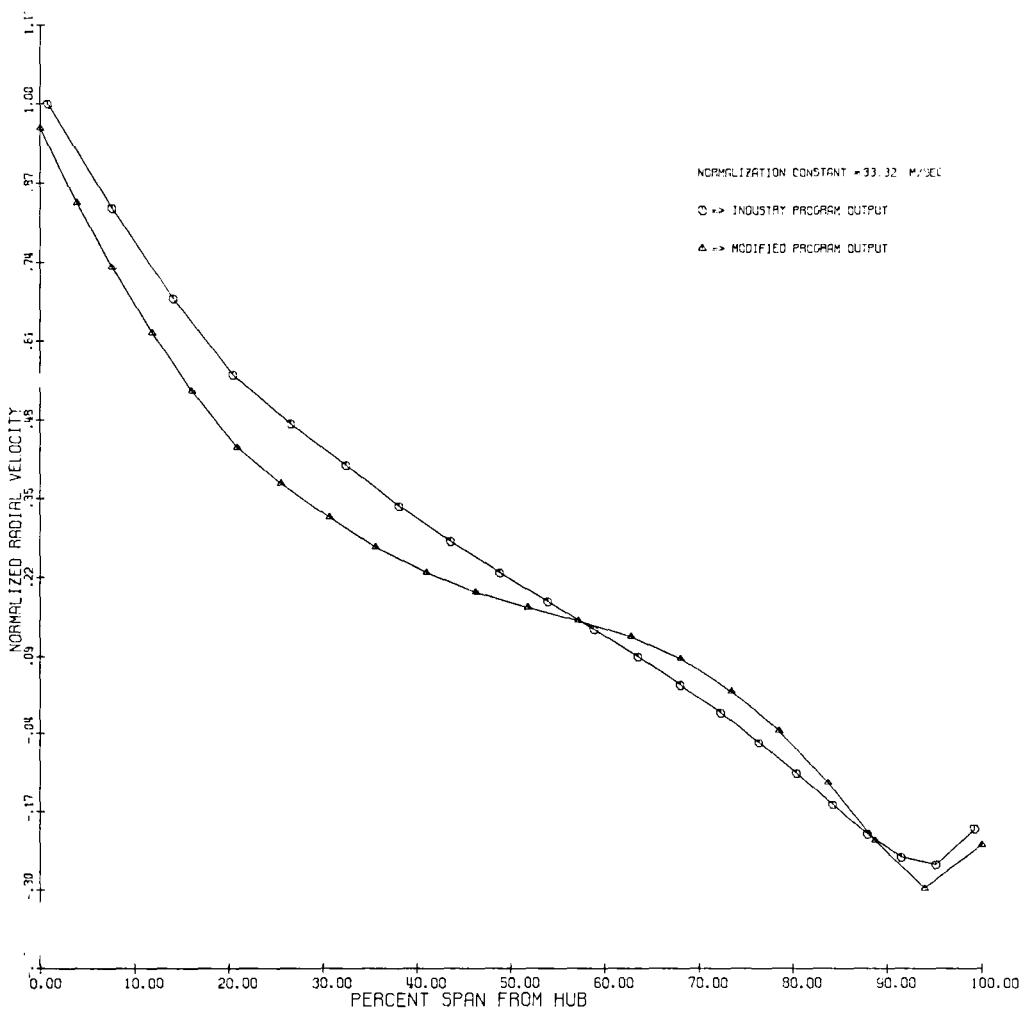
(b) Station 8.

Figure 13. - Concluded.



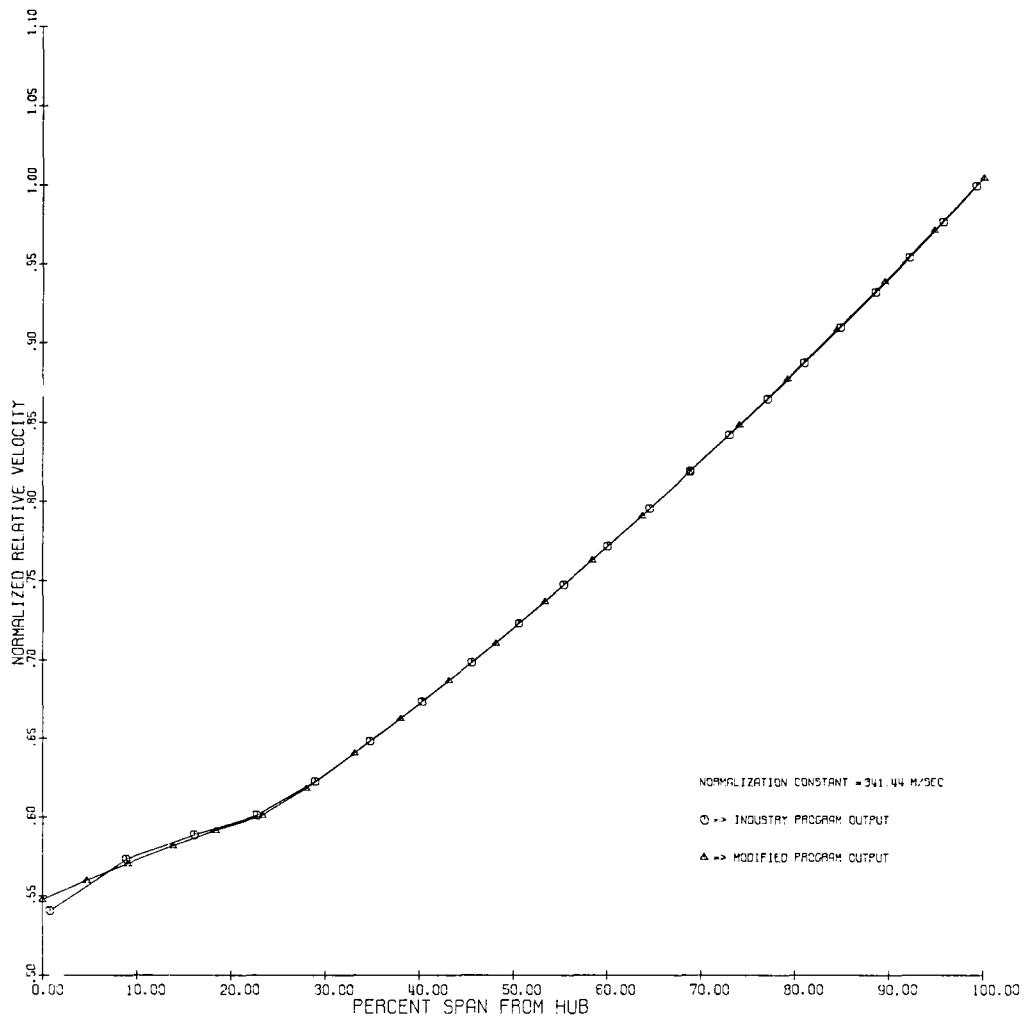
(a) Station 7.

Figure 14. - Comparison of program radial velocity output.



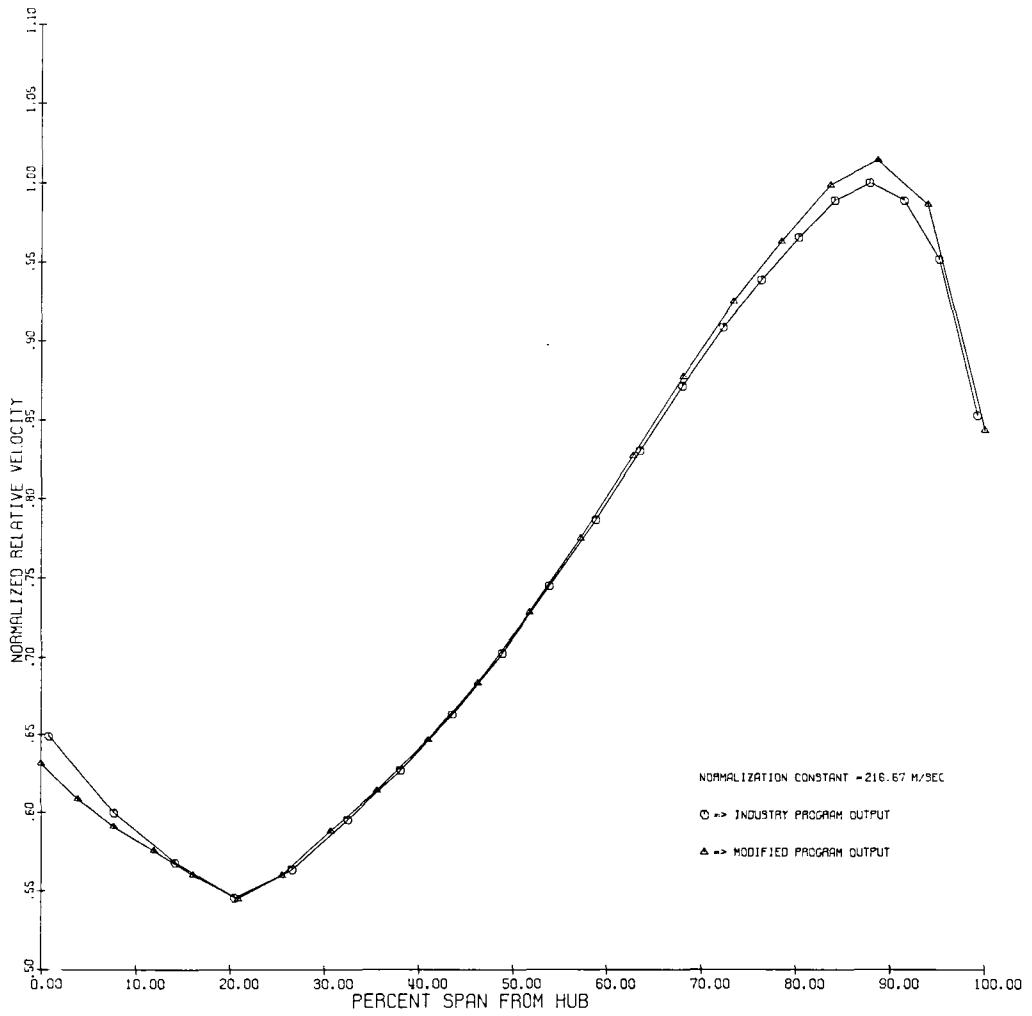
(b) Station 8.

Figure 14 - Concluded.



(a) Station 7.

Figure 15. - Comparison of program relative velocity output.



(b) Station 8.

Figure 15. - Concluded.

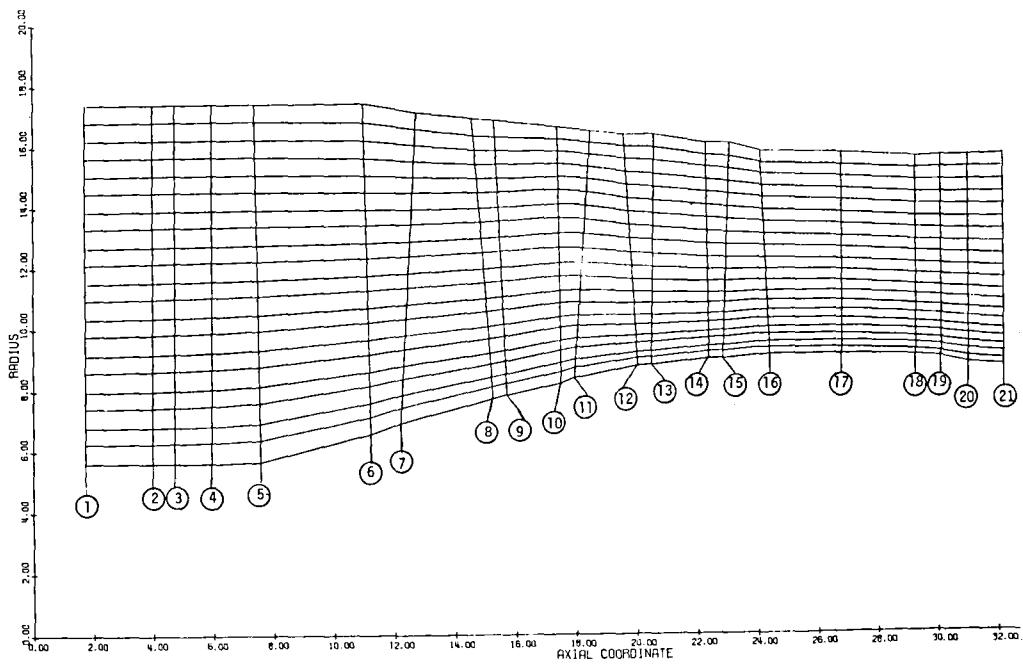


Figure 16. - Streamline contraction through fan module (program generated CALCOMP plot). One unit of length on the axes equals 2.54 cm. (1.0 inch).

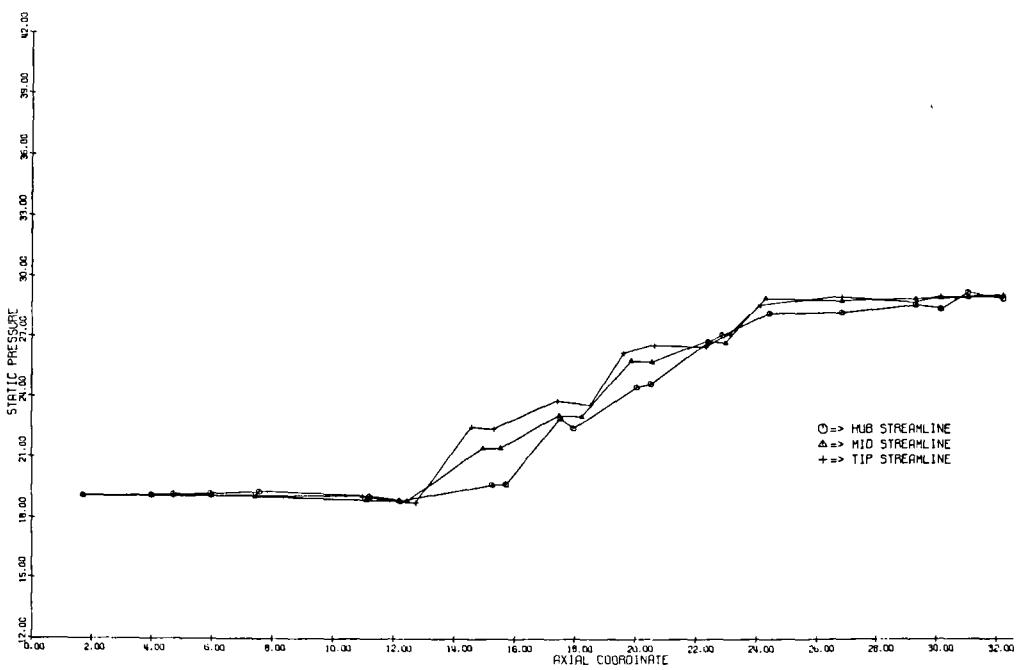


Figure 17. - Static pressure distribution in fan module (program generated CALCOMP plot). One unit of pressure equals 6.895 kPa (1.0 psia). One unit of length equals 2.54 cm. (1.0 inch).

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| 16. Abstract <p>This report describes modifications of an existing axial compressor streamline analysis computer program to allow input of measured radial pressure and temperature profiles obtained from engine or cascade data. The proposed modifications increases the input flexibility and are accomplished without changing the computer program's input format. The computer program was written by Richard M. Hearsey under a grant from the Aerospace Research Laboratory at Wright-Patterson Air Force Base. Since this report is intended to supplement the above computer program, the reader is referred to Hearsey's reports for theory, complete program listings, and detailed user's instructions.</p> | | | |
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